

# Statistical learning algorithms for biological neural networks

New Jersey Institute of Technology Biology Colloquium

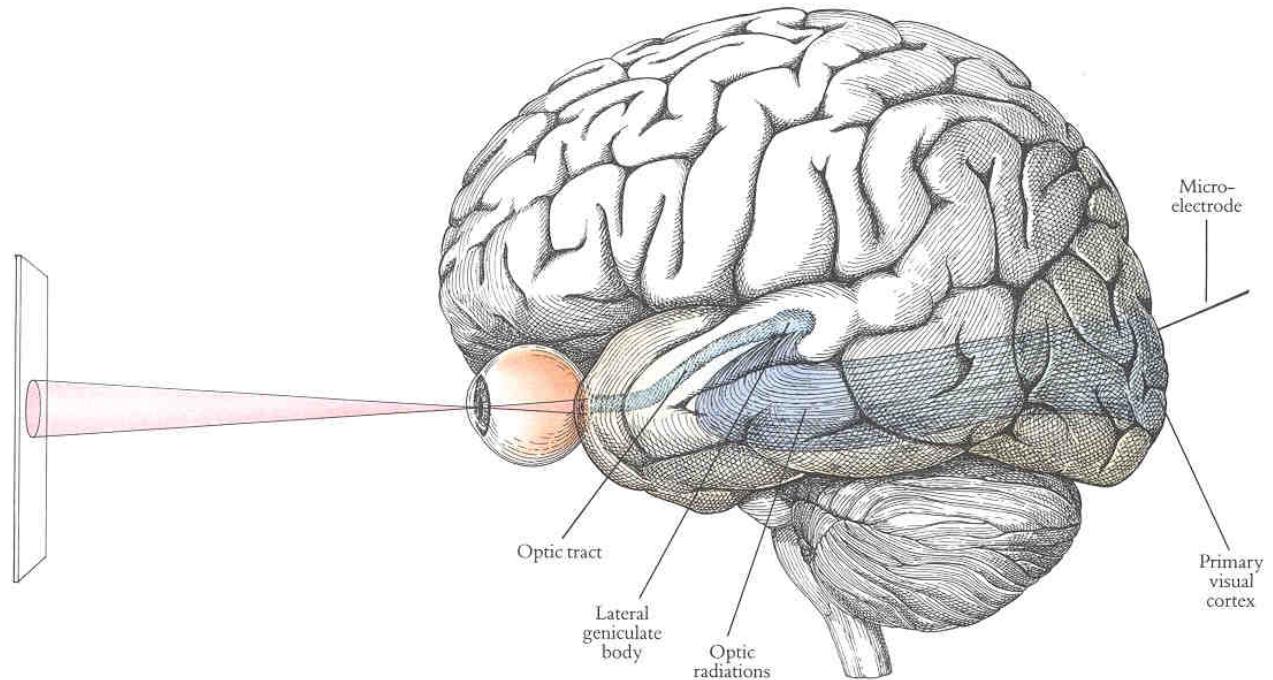
**David Lipshutz**

16 April 2024



# A theorist's view of sensory processing

Sensory systems encode natural signals as patterns of electrical activity, which are reformatted over multiple stages of processing to produce useful representations of the world.



Goal: concise mathematical descriptions  
of the statistical learning algorithms that  
support sensory processing.

Neural systems are complex. What does a  
concise mathematical description look like?

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concise mathematical description look like?

Let's contrast 2 models of single neurons.

J. Physiol. (1952) 117, 500–544

A QUANTITATIVE DESCRIPTION OF MEMBRANE  
CURRENT AND ITS APPLICATION TO CONDUCTION  
AND EXCITATION IN NERVE

By A. L. HODGKIN AND A. F. HUXLEY

$$I = C_M \frac{dV}{dt} + \bar{g}_K n^4 (V - V_K) + \bar{g}_{Na} m^3 h (V - V_{Na}) + \bar{g}_l (V - V_l),$$

$$\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n,$$

$$\frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m,$$

~20 parameters

$$\frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h,$$

$$\alpha_n = 0.01 (V + 10) / \left( \exp \frac{V + 10}{10} - 1 \right),$$

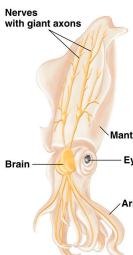
$$\beta_n = 0.125 \exp (V/80),$$

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$$\beta_h = 1 / \left( \exp \frac{V + 30}{10} + 1 \right).$$



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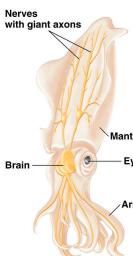
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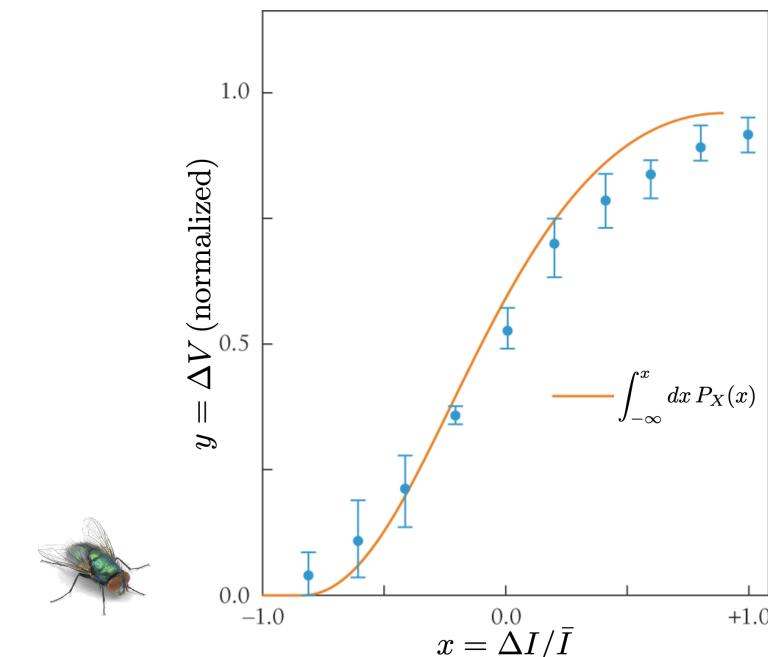


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A Simple Coding Procedure Enhances a Neuron's Information Capacity

Simon Laughlin

Z. Naturforsch. 36 c, 910–912 (1981)



Based on theories of **Efficient Coding** [Barlow 1961, Attneave 1954] and **Communication** [Shannon 1948]. Other successful examples [Dan et al. 1996; Bell & Sejnowski 1995, 1997; Olshausen & Field 1996; Brenner et al. 2000; Pitkow & Meister 2012; Palmer et al. 2015; ...]

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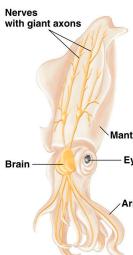
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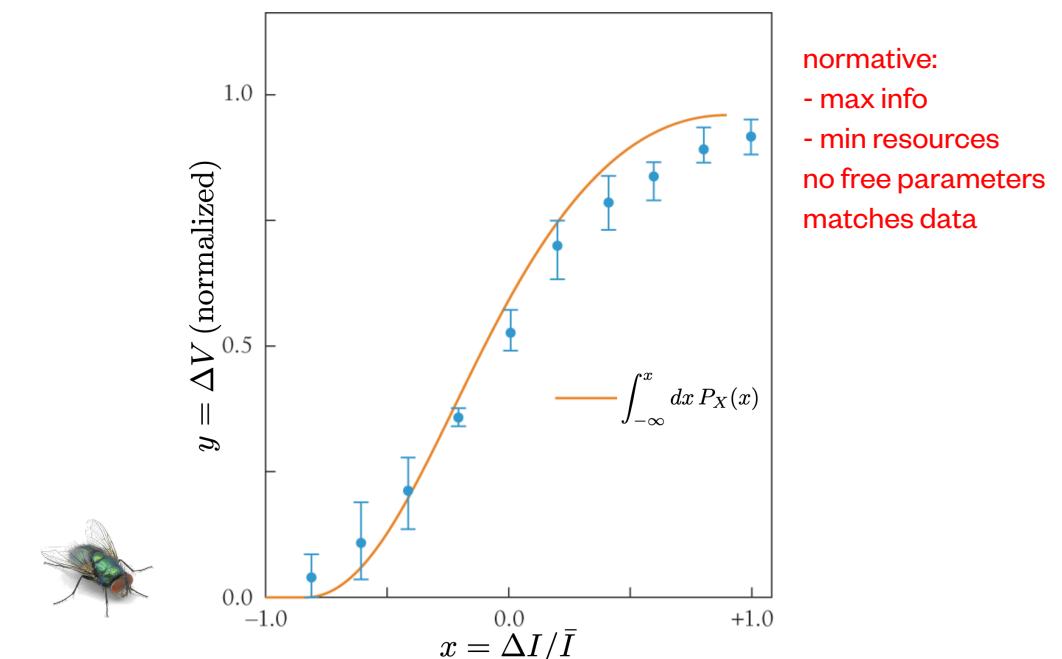
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## A Simple Coding Procedure Enhances a Neuron's Information Capacity

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- normative:
- max info
  - min resources
  - no free parameters
  - matches data

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How do we apply this approach to learning in neural systems?

## Wish list for learning algorithms:

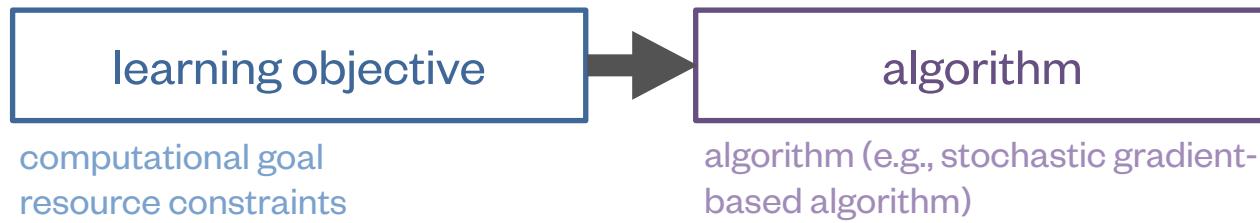
1. normative (principled)
2. sample efficient (good implicit bias, low sample complexity)
3. resource efficient (local, online, sparse, spiking, etc.)
4. no free parameters (parameters matched to input stats)
5. matches neural data (anatomical, physiological)

## Normative framework for deriving biological learning algorithms

learning objective

computational goal  
resource constraints

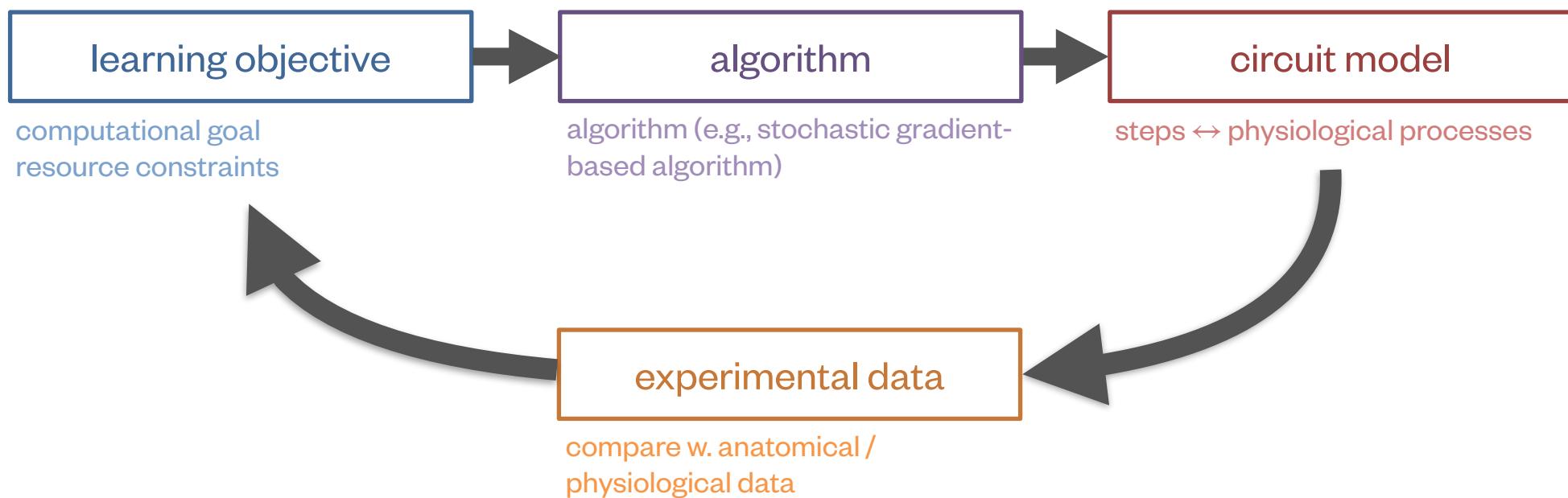
## Normative framework for deriving biological learning algorithms



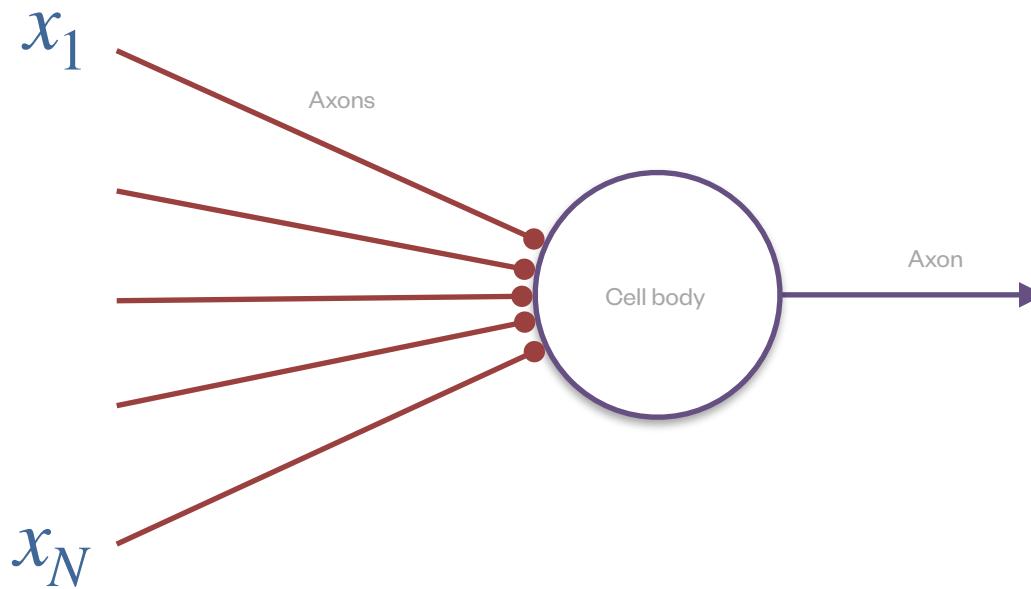
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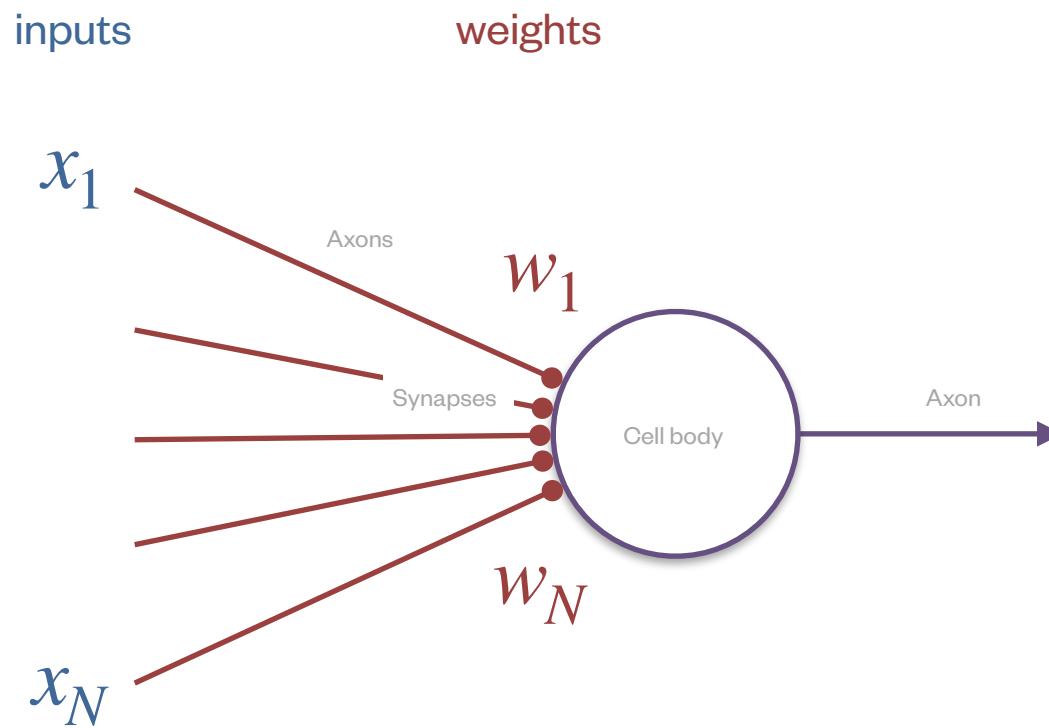


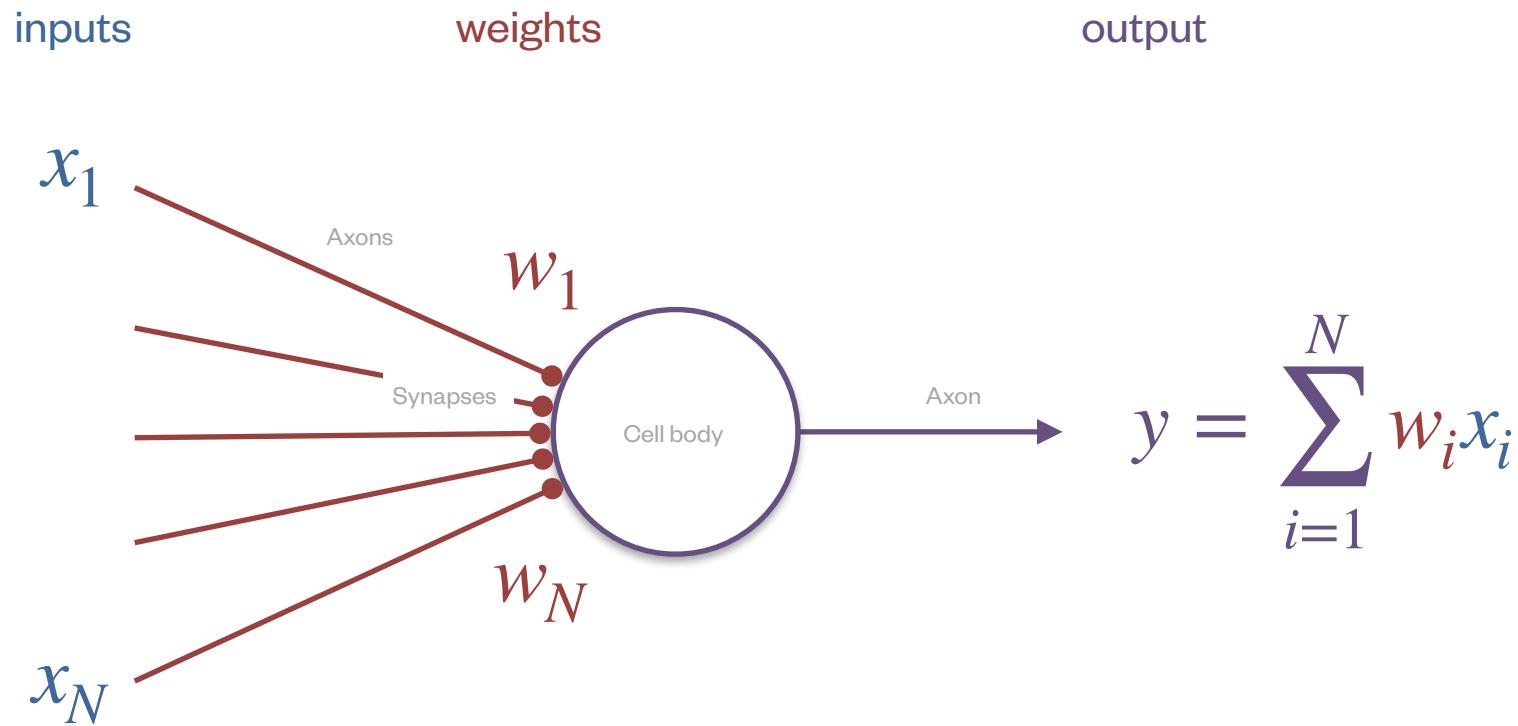
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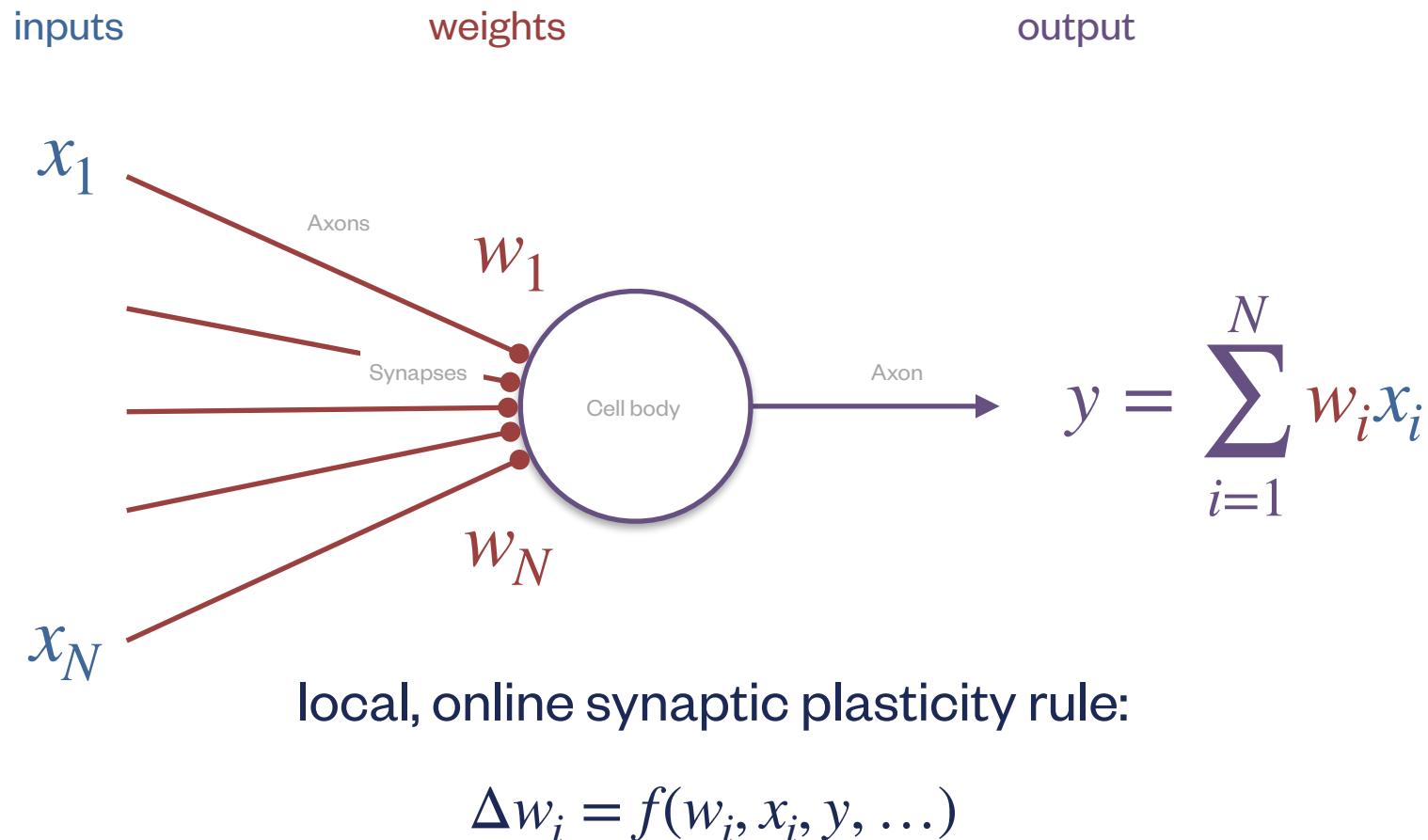


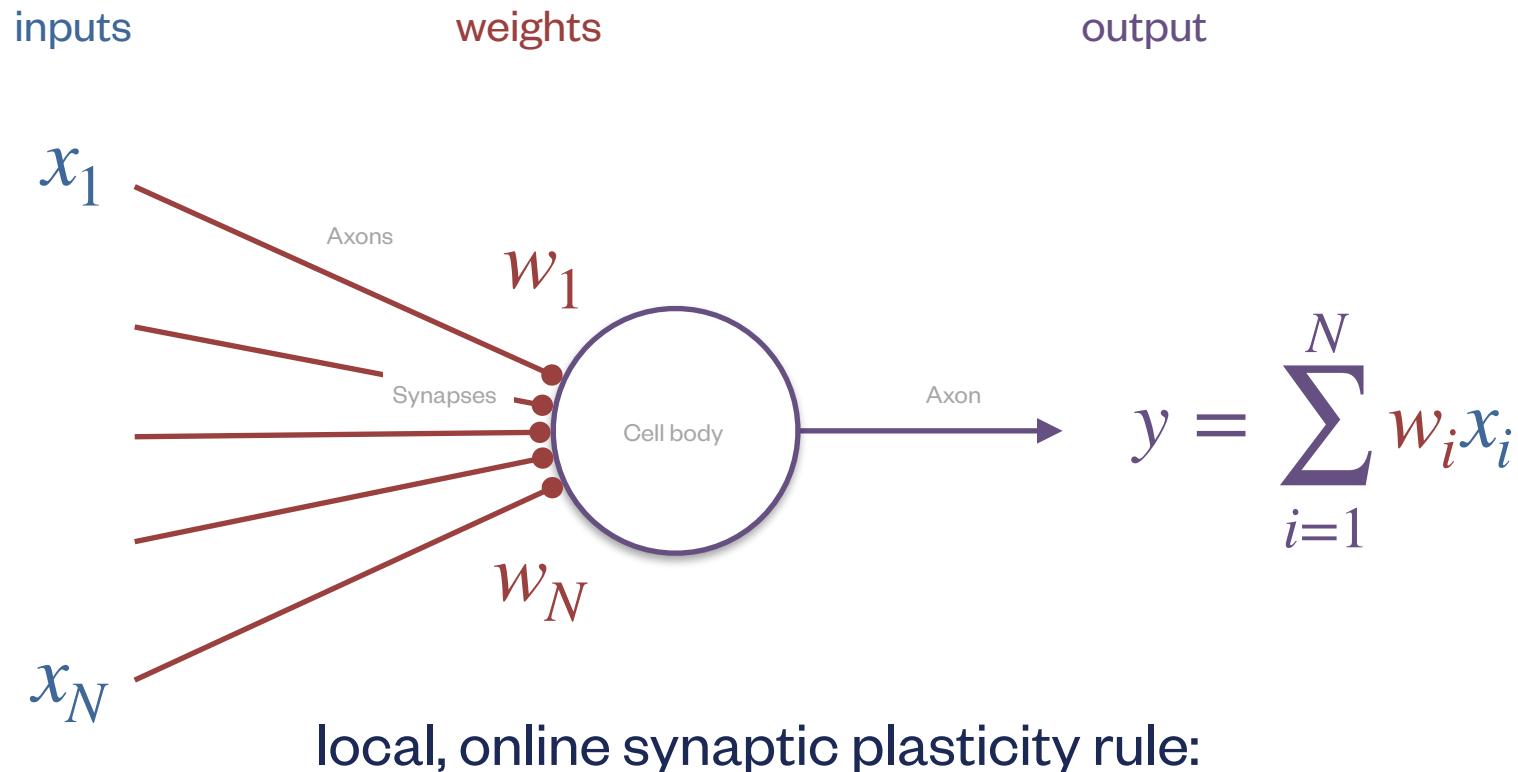
inputs











local, online synaptic plasticity rule:

$$\Delta w_i = f(w_i, x_i, y, \dots)$$

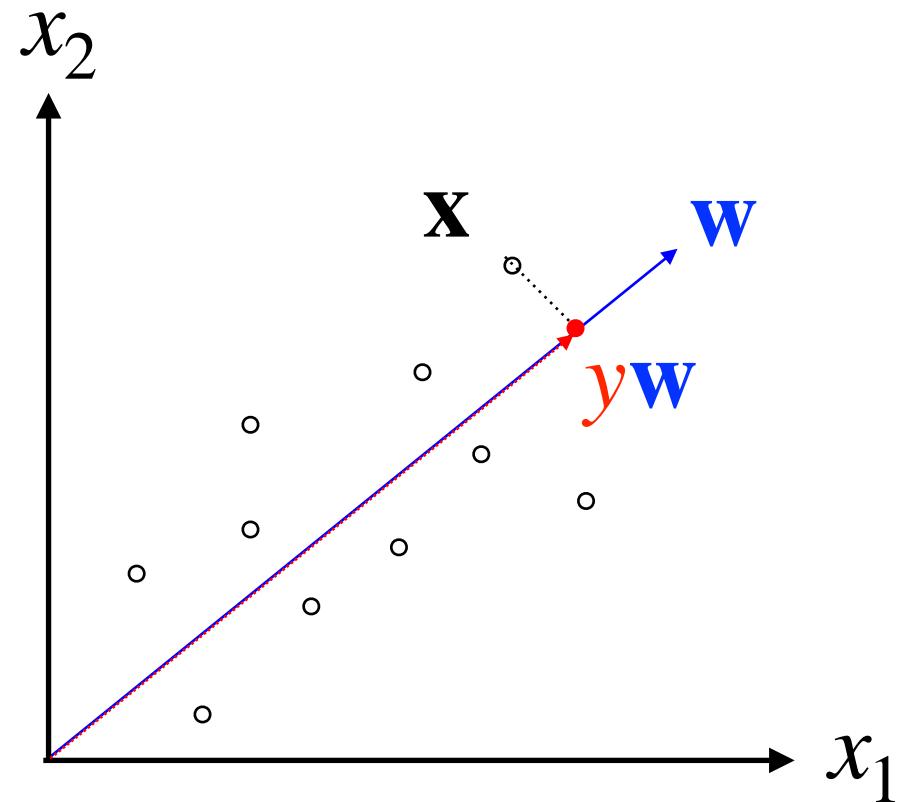
**Goal:** connect plasticity rules & learning objectives

**Normative principle:** maximize *information*

$$\min_w \mathbb{E} [\|\mathbf{x} - \mathbf{w}\mathbf{w}^\top \mathbf{x}\|^2]$$

# Oja's PCA model of a neuron

Oja 1982



# Oja's PCA model of a neuron

**Normative principle:** maximize *information*

$$\min_{\mathbf{w}} \mathbb{E} [\|\mathbf{x} - \mathbf{w}\mathbf{w}^T \mathbf{x}\|^2]$$



$$y = \mathbf{w}^T \mathbf{x}$$

$$\Delta w_i = \eta (y x_i - y^2 w_i)$$

Hebbian      homeostatic

Oja 1982

# Oja's PCA model of a neuron

Oja 1982

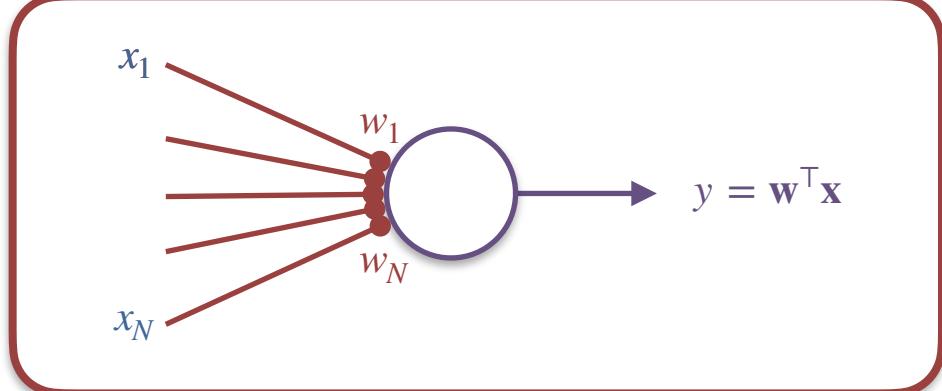
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# Oja's PCA model of a neuron

Oja 1982

Neural algorithms wish list:

1. principled? maximizes info transmission (for Gaussian inputs)
2. sample efficient? matches info theoretic LB [Chou & Wang 2020]
3. resource efficient? local & online
4. free parameters? learning rate  $\eta$
5. match data? predicts connectomic data [Chapochnikov et al. 2023]

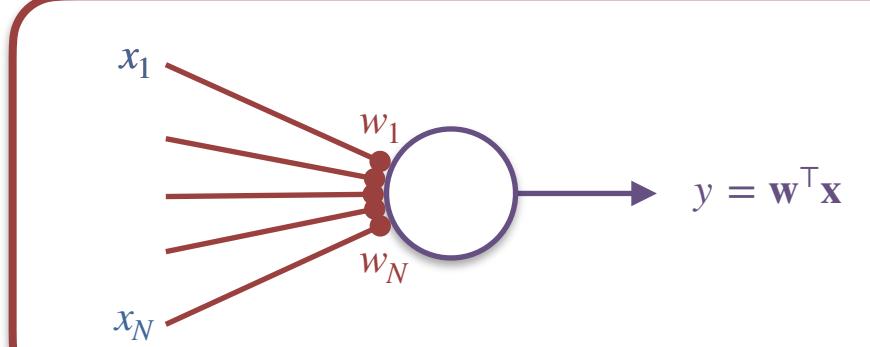
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$$\Delta w_i = \eta (y x_i - y^2 w_i)$$

Hebbian      homeostatic



# Biological extensions of Oja's algorithm

Multichannel PCA (normative + local) [Pehlevan, Hu & Chklovskii 2015]

Manifold tiling [Sengupta et al. 2018]

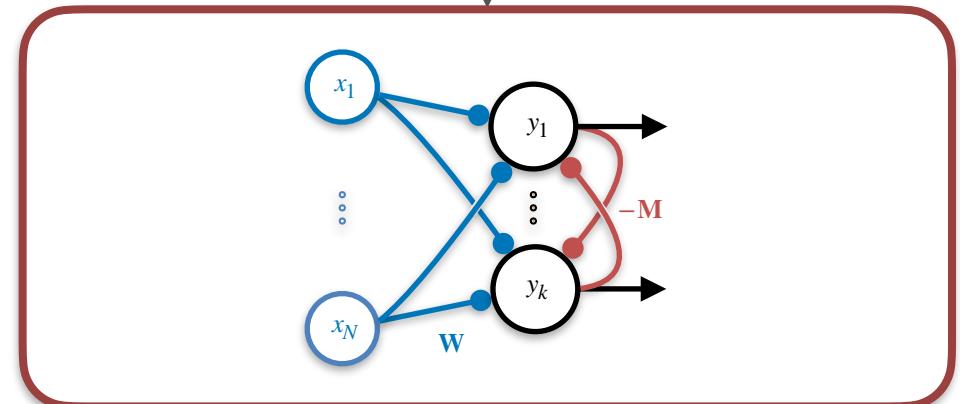
**Normative principle:** maximize *information*

$$\min_{\{\mathbf{y}_t\}} \sum_{t=1}^T \sum_{t'=1}^T (\mathbf{y}_t^\top \mathbf{y}_{t'} - \mathbf{x}_t^\top \mathbf{x}_{t'})^2$$

Neural dynamics:  $\mathbf{y} \leftarrow \mathbf{y} + \gamma(\mathbf{W}\mathbf{x} - \mathbf{M}\mathbf{y})$

$$\Delta \mathbf{W} \propto \mathbf{y}\mathbf{x}^\top - \mathbf{W} \quad \Delta \mathbf{M} \propto \mathbf{y}\mathbf{y}^\top - \mathbf{M}$$

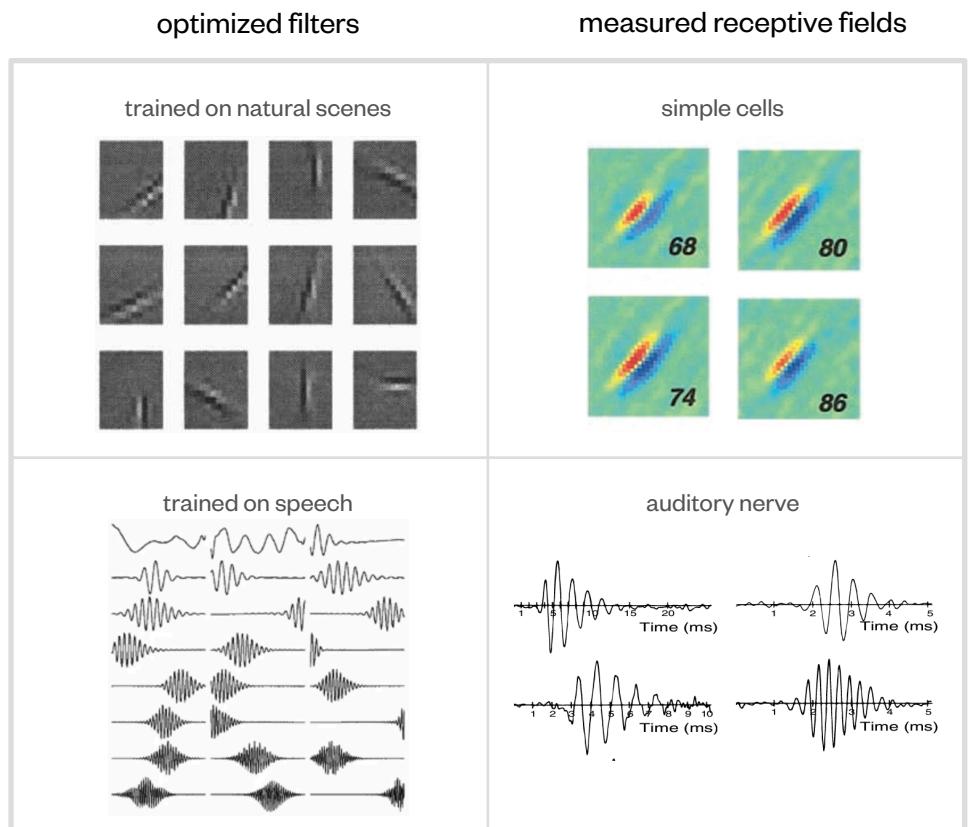
Hebbian      homeostatic      anti-Hebbian      homeostatic



Limitation #1: Doesn't account for other learning principles.

## Independent Component Analysis (ICA)

**Normative principle:** relevant features are *independent*

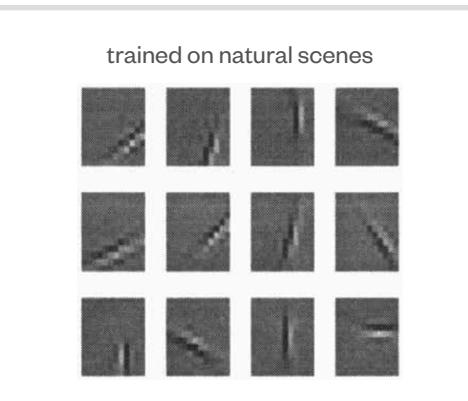


[Olshausen & Field 1997; Bell & Sejnowski 1995, 1997; van Hateren & van der Schaaf 1998;  
 Hubel & Wiesel 1959; Ringach 2002; Lewicki 2002; de Boer & de Jongh 1978]

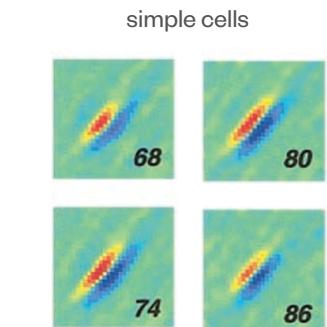
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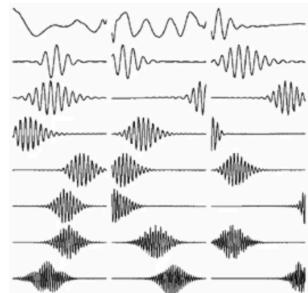
optimized filters



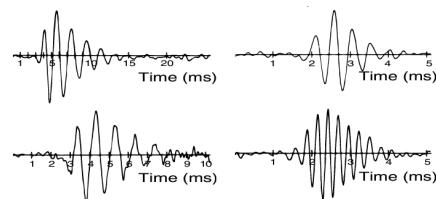
measured receptive fields



trained on speech



auditory nerve

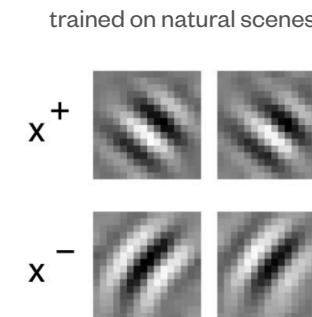


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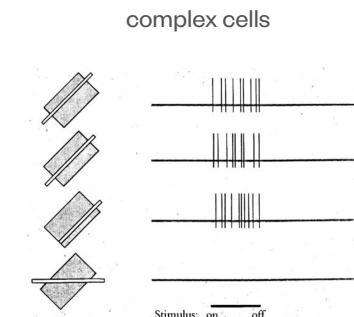
## Slow Feature Analysis (SFA)

**Normative principle:** relevant features are *slow*

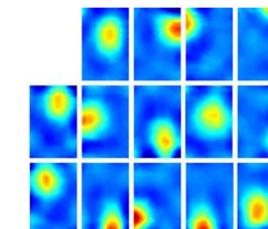
optimized filters



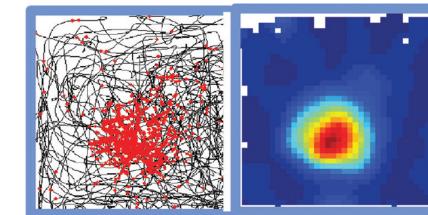
measured receptive fields



trained on simulated visual inputs during virtual navigation



place cells



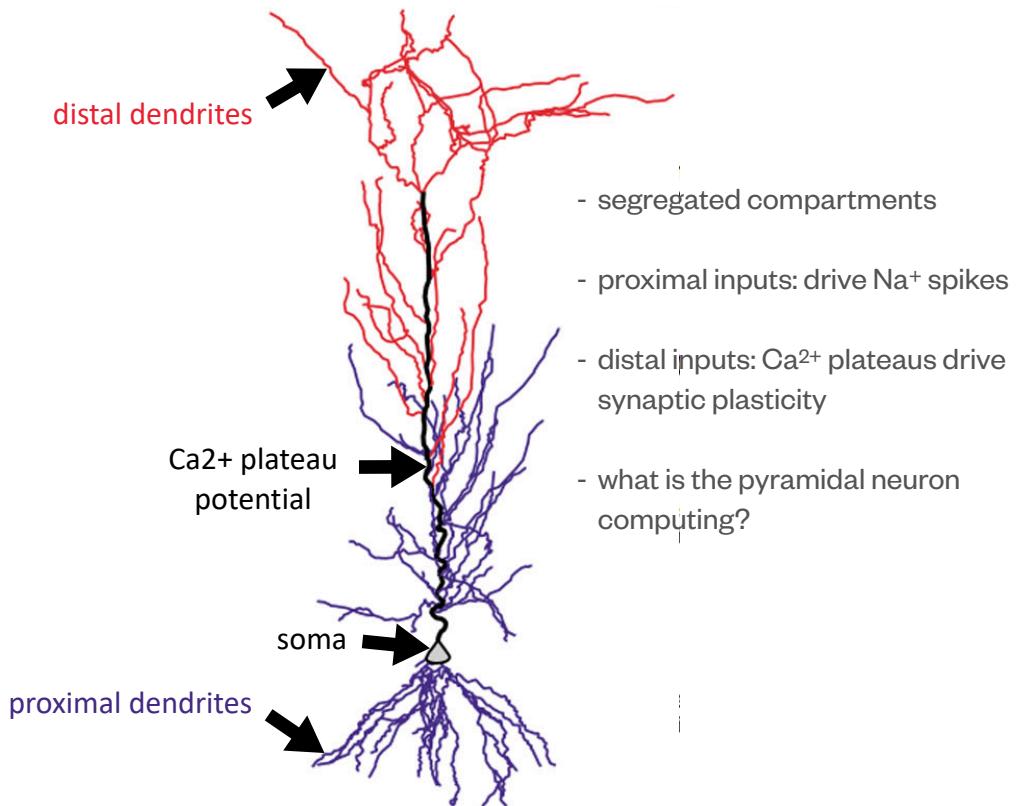
[Földiák 1991; Wiskott & Sejnowski 2002; Berkes et al. 2007; Franzius, Sprekeler & Wiskott 2007; Hubel & Wiesel 1968; O'Keefe & Dostrovsky 1971]

Limitation #1: Doesn't account for other learning principles.

Limitation #2: Cannot explain **multicompartmental neurons** or **non-Hebbian** synaptic plasticity rules.

## CA1 pyramidal neuron (axon omitted)

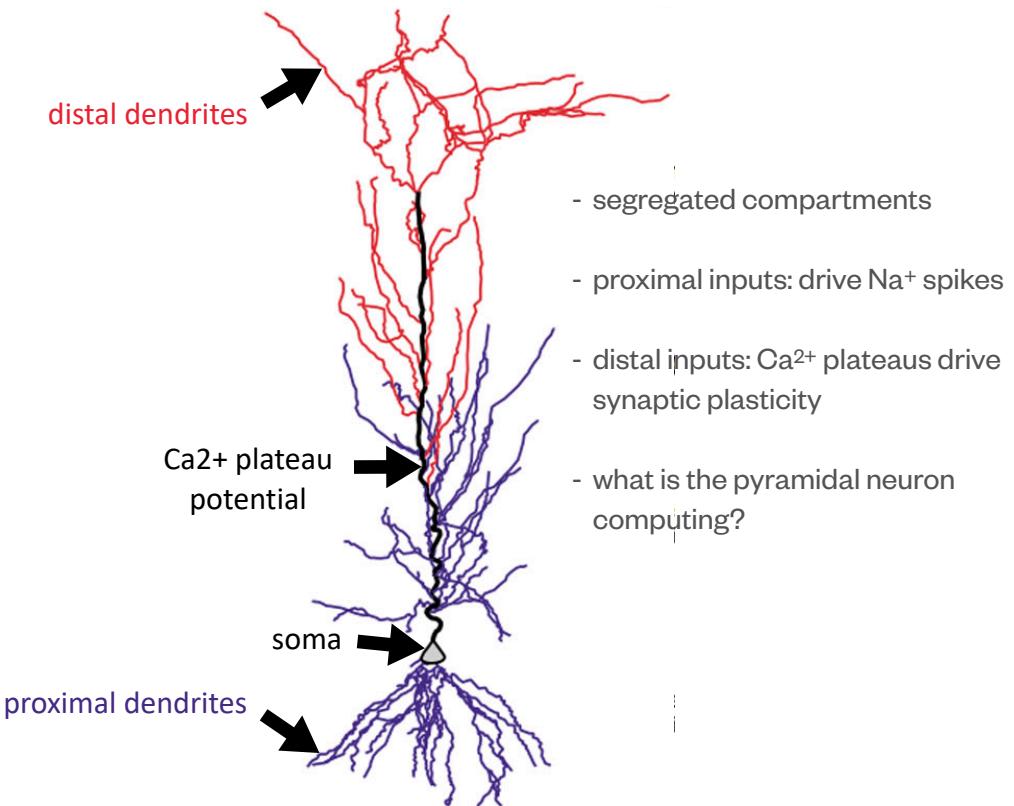
[Häusser & Mel 2003]



**Experimental:** Schiller et al. 1997; Larkum et al. 1999; Takahashi & Magee 2009; Bittner et al. 2015; ... **Computational:** Körding & König 2001; Poirazi et al. 2003; Urbanczik & Senn 2014; Guerguev et al. 2017; Whittington & Bogacz 2017; Sacramento et al. 2018; Milstein et al. 2021; ...

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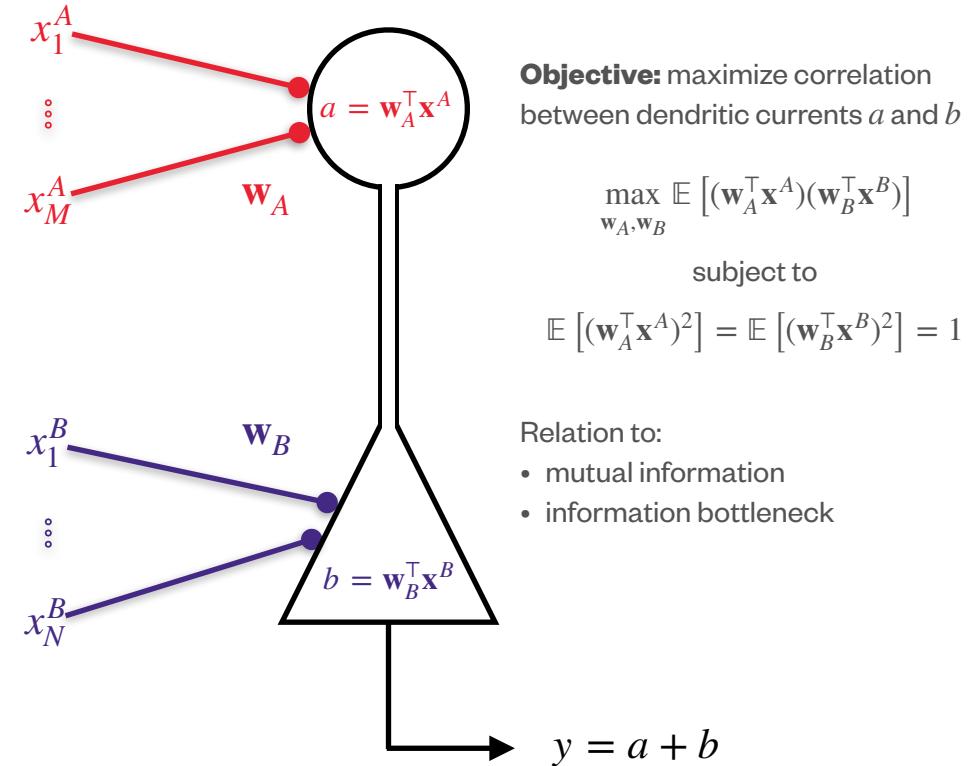
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## Canonical Correlation Analysis (CCA)

**Normative principle:** relevant features are *correlated*



[Hotelling 1936; Tishby, Pereira & Bialek 2000; Chechik et al. 2003; Lipshutz et al. 2021; Barreiro et al. 2024]

Goal: relate these learning principles  
(independence, slowness, correlation, etc.)  
to synaptic plasticity rules



# A unified framework: symmetric generalized eigenvalue problems

$$\mathbf{Aw} = \lambda \mathbf{Bw}$$

$$\mathbf{A} = \mathbb{E} [\boldsymbol{\xi}_t \boldsymbol{\xi}_t^\top] \quad \mathbf{B} = \mathbb{E} [\mathbf{B}_t]$$

Existing algorithms for solving generalized eigenvalue problems do not map onto biological NNs

[Arora et al. 2017, Bhatia et al. 2018]

Lipshutz\*, Bahroun\*, Golkar\* et al. *PRX Life* 2023

Learning task	$\boldsymbol{\xi}_t$	$\mathbf{B}_t$
PCA	$\mathbf{x}_t$	$\mathbf{I}$
ICA	$\mathbf{x}_t$	$\ \mathbf{C}_X^{-1/2} \mathbf{x}_t\ ^2 \mathbf{x}_t \mathbf{x}_t^\top$
SFA	$\mathbf{x}_t + \mathbf{x}_{t-1}$	$\mathbf{x}_t \mathbf{x}_t^\top$
CCA	$\begin{bmatrix} \mathbf{x}_t^A \\ \mathbf{x}_t^B \end{bmatrix}$	$\begin{bmatrix} \mathbf{x}_t^A \mathbf{x}_t^{A,\top} \\ & \mathbf{x}_t^B \mathbf{x}_t^{B,\top} \end{bmatrix}$
contrastive PCA	$\delta_t \mathbf{x}_t$	$(1 - \delta_t) \mathbf{x}_t \mathbf{x}_t^\top$

$$\min_{\zeta_t \in \mathbb{R}^k} \sum_{t=1}^T \sum_{t'=1}^T (\xi_t^\top \mathbf{B}^{-1} \xi_{t'} - \zeta_t^\top \zeta_{t'})^2$$

opt.  $\zeta_t$  = proj. of  $\xi_t$  onto  $k$ -eigensubspace

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input  
similarity

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input      output  
similarity    similarity

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input                      output  
 similarity                similarity

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input-output  
correlation

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input-output  
 correlation                output-output  
 correlation

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input similarity      output similarity

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input-output correlation      output-output correlation

$$\min_{\mathbf{W}} \max_{\mathbf{M}} \frac{1}{T} \sum_{t=1}^T \min_{\zeta_t} \ell(\mathbf{W}, \mathbf{M}, \xi_t, \mathbf{B}_t, \zeta_t)$$

$$\ell(\mathbf{W}, \mathbf{M}, \xi_t, \mathbf{B}_t, \zeta_t) = -4\zeta_t^\top \mathbf{W} \xi_t + 2\zeta_t^\top \mathbf{M} \zeta_t + 2\text{Tr}(\mathbf{W} \mathbf{B}_t \mathbf{W}^\top) - \text{Tr}(\mathbf{M}^2)$$

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input similarity      output similarity

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feedforward weights

$$\min_{\xi_t \in \mathbb{R}^k} \sum_{t=1}^T \sum_{t'=1}^T (\xi_t^\top \mathbf{B}^{-1} \xi_{t'} - \zeta_t^\top \zeta_{t'})^2$$

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$$\ell(\mathbf{W}, \mathbf{M}, \xi_t, \mathbf{B}_t, \zeta_t) = -4\zeta_t^\top \mathbf{W} \xi_t + 2\zeta_t^\top \mathbf{M} \zeta_t + 2\text{Tr}(\mathbf{W} \mathbf{B}_t \mathbf{W}^\top) - \text{Tr}(\mathbf{M}^2)$$

feedforward weights      recurrent weights

$$\min_{\xi_t \in \mathbb{R}^k} \sum_{t=1}^T \sum_{t'=1}^T (\xi_t^\top \mathbf{B}^{-1} \xi_{t'} - \zeta_t^\top \zeta_{t'})^2$$

input                      output  
similarity

Optimizing  $\zeta_t$  over  $\mathbb{R}_+^k$  leads to  
Nonnegative Matrix Factorization

subspace

$$\min_{\zeta_t} \sum_{t=1}^T \left[ -2\zeta_t^\top \left( \sum_{t'=1}^T \zeta_{t'} \xi_{t'}^\top \mathbf{B}^{-1} \right) \xi_t + \zeta_t^\top \left( \sum_{t'=1}^T \zeta_{t'} \zeta_{t'}^\top \right) \zeta_t \right]$$

input-output  
correlation              output-output  
correlation

$$\min_{\mathbf{W}} \max_{\mathbf{M}} \frac{1}{T} \sum_{t=1}^T \min_{\zeta_t} \ell(\mathbf{W}, \mathbf{M}, \xi_t, \mathbf{B}_t, \zeta_t)$$

$$\ell(\mathbf{W}, \mathbf{M}, \xi_t, \mathbf{B}_t, \zeta_t) = -4\xi_t^\top \mathbf{W} \xi_t + 2\xi_t^\top \mathbf{M} \zeta_t + 2\text{Tr}(\mathbf{W} \mathbf{B}_t \mathbf{W}^\top) - \text{Tr}(\mathbf{M}^2)$$

feedforward              recurrent  
weights                  weights

$$\min_{\mathbf{W}} \max_{\mathbf{M}} \frac{1}{T} \sum_{t=1}^T \min_{\boldsymbol{\xi}_t} \ell(\mathbf{W}, \mathbf{M}, \boldsymbol{\xi}_t, \mathbf{B}_t, \boldsymbol{\zeta}_t)$$

$$\ell(\mathbf{W}, \mathbf{M}, \boldsymbol{\xi}_t, \mathbf{B}_t, \boldsymbol{\zeta}_t) = -4\boldsymbol{\xi}_t^\top \text{feedforward weights} \mathbf{W} \boldsymbol{\xi}_t + 2\boldsymbol{\xi}_t^\top \text{recurrent weights} \mathbf{M} \boldsymbol{\xi}_t + 2\text{Tr}(\mathbf{W}\mathbf{B}_t\mathbf{W}^\top) - \text{Tr}(\mathbf{M}^2)$$

$$\min_{\mathbf{W}} \max_{\mathbf{M}} \frac{1}{T} \sum_{t=1}^T \min_{\boldsymbol{\xi}_t} \ell(\mathbf{W}, \mathbf{M}, \boldsymbol{\xi}_t, \mathbf{B}_t, \boldsymbol{\zeta}_t)$$

$$\ell(\mathbf{W}, \mathbf{M}, \boldsymbol{\xi}_t, \mathbf{B}_t, \boldsymbol{\zeta}_t) = -4\boldsymbol{\zeta}_t^\top \mathbf{W} \boldsymbol{\xi}_t + 2\boldsymbol{\zeta}_t^\top \mathbf{M} \boldsymbol{\zeta}_t + 2\text{Tr}(\mathbf{W} \mathbf{B}_t \mathbf{W}^\top) - \text{Tr}(\mathbf{M}^2)$$

feedforward recurrent  
weights weights



```

input  $\{(\boldsymbol{\xi}_t, \mathbf{B}_t)\}$ ; parameters  $\gamma > 0$  and  $0 < \eta < \tau$ 
initialize  $\mathbf{W} \in \mathbb{R}^{k \times n}$  and  $\mathbf{M} \in \mathbb{S}_{++}^k$ 
for  $t = 1, 2, \dots$  do
    repeat
         $\boldsymbol{\zeta}_t \leftarrow \boldsymbol{\zeta}_t + \gamma(\mathbf{W} \boldsymbol{\xi}_t - \mathbf{M} \boldsymbol{\zeta}_t)$  // recurrent neural dynamics
    until convergence
     $\mathbf{W} \leftarrow \mathbf{W} + 2\eta(\boldsymbol{\zeta}_t \boldsymbol{\zeta}_t^\top - \mathbf{W} \mathbf{B}_t)$  // feedforward synaptic updates
     $\mathbf{M} \leftarrow \mathbf{M} + \frac{\eta}{\tau}(\boldsymbol{\zeta}_t \boldsymbol{\zeta}_t^\top - \mathbf{M})$  // recurrent synaptic updates
end for

```

```

input  $\{(\xi_t, \mathbf{B}_t)\}$ ; parameters  $\gamma > 0$  and  $0 < \eta < \tau$ 
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     $\mathbf{M} \leftarrow \mathbf{M} + \frac{\eta}{\tau}(\xi_t \xi_t^\top - \mathbf{M})$  // recurrent synaptic updates
end for

```

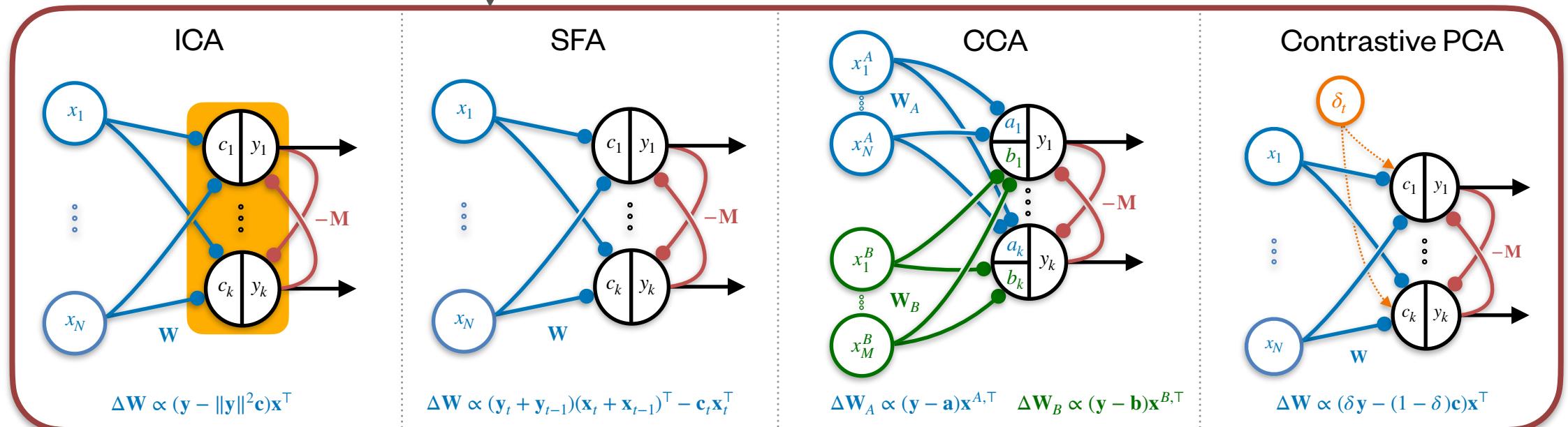
Learning task	$\xi_t$	$\mathbf{B}_t$
PCA	$\mathbf{x}_t$	$\mathbf{I}$
ICA	$\mathbf{x}_t$	$\ \mathbf{C}_X^{-1/2}\mathbf{x}_t\ ^2 \mathbf{x}_t \mathbf{x}_t^\top$
SFA	$\mathbf{x}_t + \mathbf{x}_{t-1}$	$\mathbf{x}_t \mathbf{x}_t^\top$
CCA	$\begin{bmatrix} \mathbf{x}_t^A \\ \mathbf{x}_t^B \end{bmatrix}$	$\begin{bmatrix} \mathbf{x}_t^A \mathbf{x}_t^{A,\top} \\ \mathbf{x}_t^B \mathbf{x}_t^{B,\top} \end{bmatrix}$
contrastive PCA	$\delta_t \mathbf{x}_t$	$(1 - \delta_t) \mathbf{x}_t \mathbf{x}_t^\top$

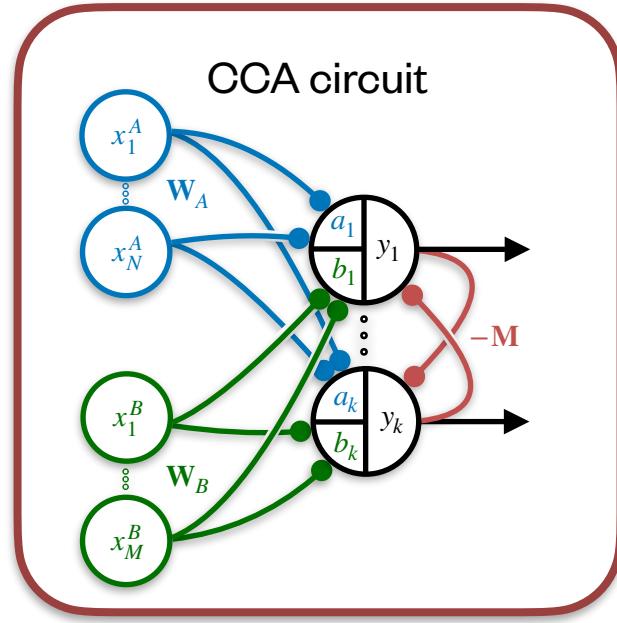
```

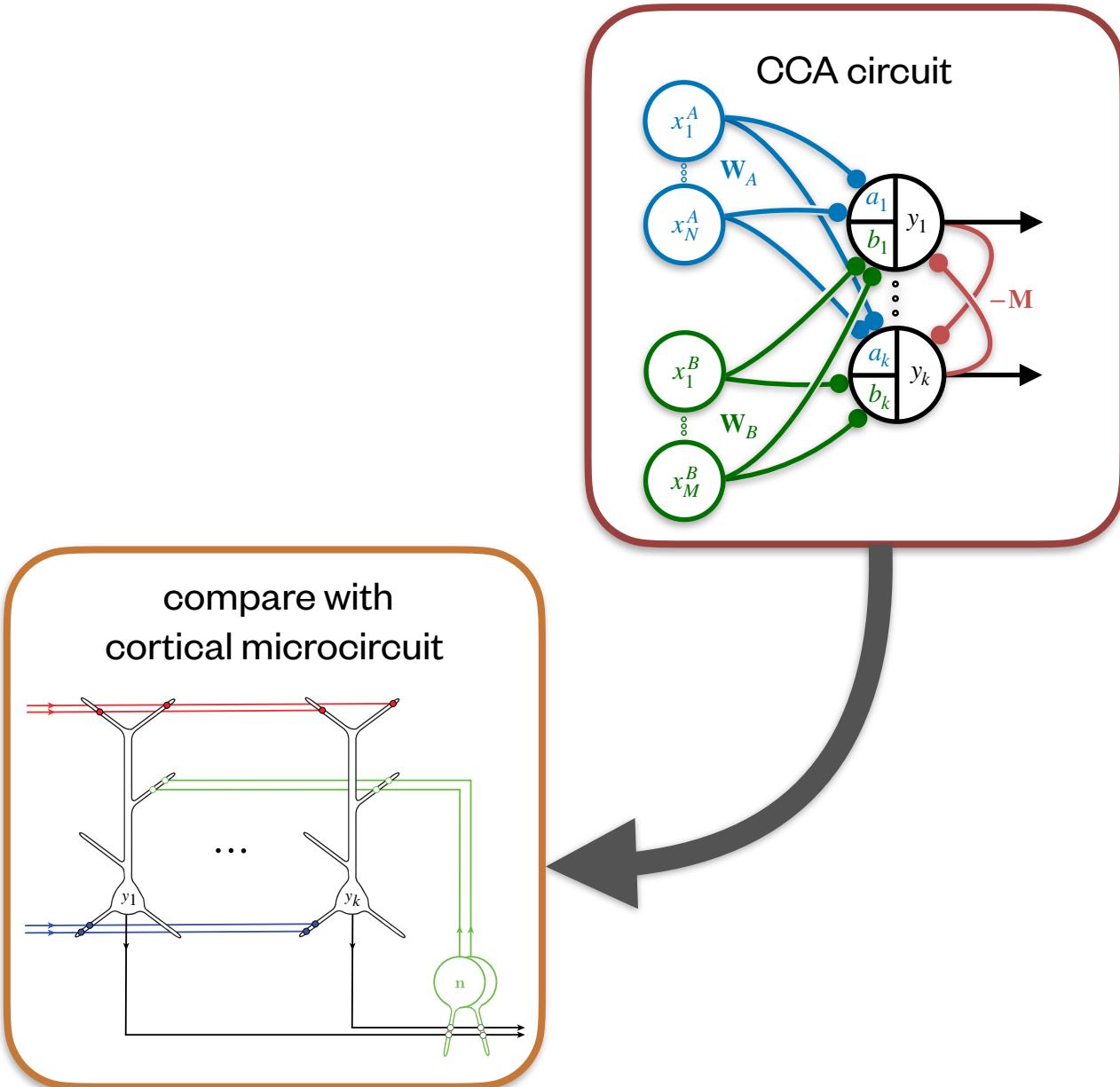
input  $\{(\xi_t, \mathbf{B}_t)\}$ ; parameters  $\gamma > 0$  and  $0 < \eta < \tau$ 
initialize  $\mathbf{W} \in \mathbb{R}^{k \times n}$  and  $\mathbf{M} \in \mathbb{S}_{++}^k$ 
for  $t = 1, 2, \dots$  do
  repeat
     $\xi_t \leftarrow \xi_t + \gamma(\mathbf{W}\xi_t - \mathbf{M}\xi_t)$  // recurrent neural dynamics
  until convergence
   $\mathbf{W} \leftarrow \mathbf{W} + 2\eta(\xi_t \xi_t^\top - \mathbf{W}\mathbf{B}_t)$  // feedforward synaptic updates
   $\mathbf{M} \leftarrow \mathbf{M} + \frac{\eta}{\tau}(\xi_t \xi_t^\top - \mathbf{M})$  // recurrent synaptic updates
end for

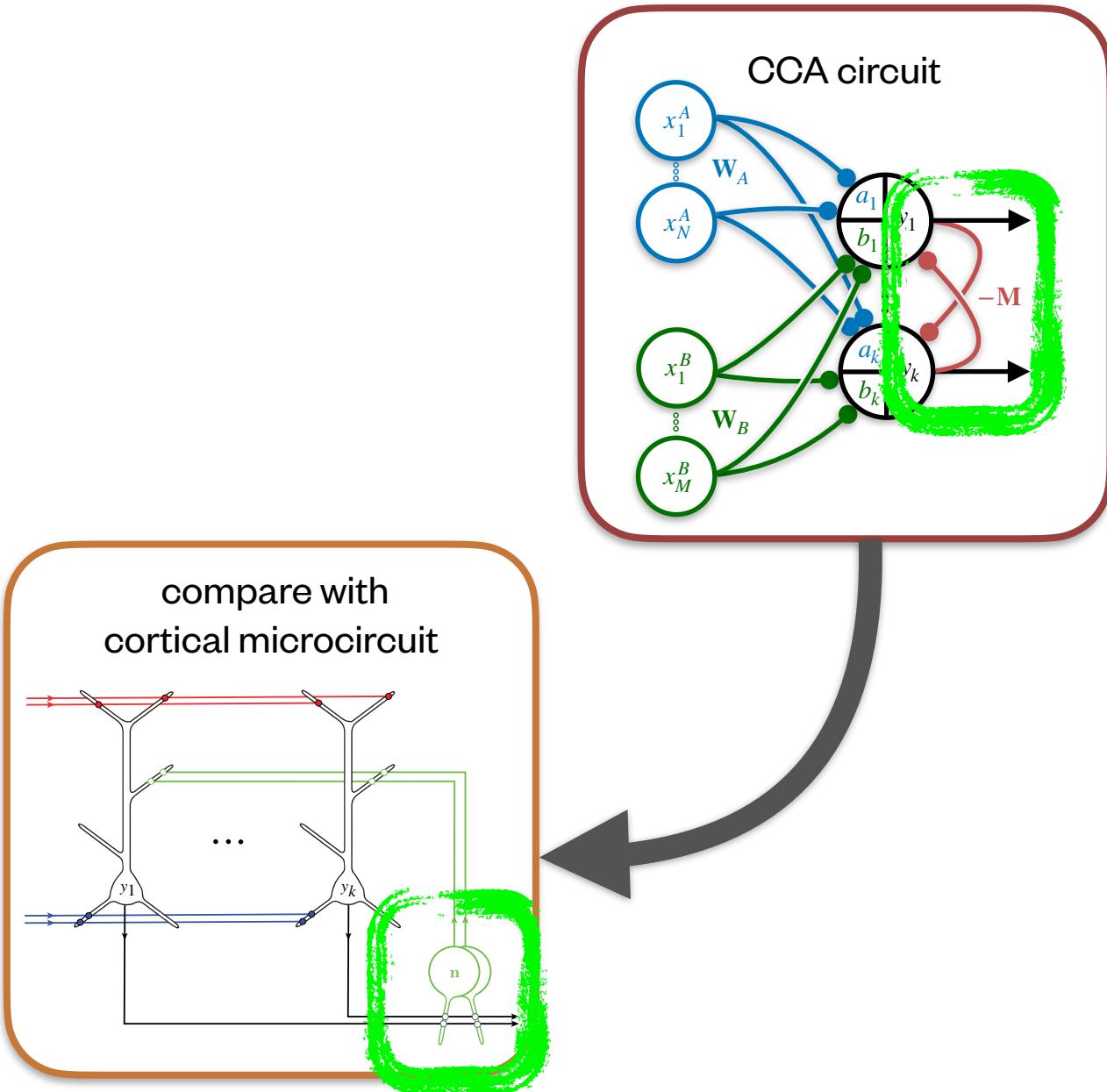
```

Learning task	$\xi_t$	$\mathbf{B}_t$
PCA	$\mathbf{x}_t$	$\mathbf{I}$
ICA	$\mathbf{x}_t$	$\ \mathbf{C}_X^{-1/2}\mathbf{x}_t\ ^2 \mathbf{x}_t \mathbf{x}_t^\top$
SFA	$\mathbf{x}_t + \mathbf{x}_{t-1}$	$\mathbf{x}_t \mathbf{x}_t^\top$
CCA	$\begin{bmatrix} \mathbf{x}_t^A \\ \mathbf{x}_t^B \end{bmatrix}$	$\begin{bmatrix} \mathbf{x}_t^A \mathbf{x}_t^{A,\top} \\ \mathbf{x}_t^B \mathbf{x}_t^{B,\top} \end{bmatrix}$
contrastive PCA	$\delta_t \mathbf{x}_t$	$(1 - \delta_t) \mathbf{x}_t \mathbf{x}_t^\top$







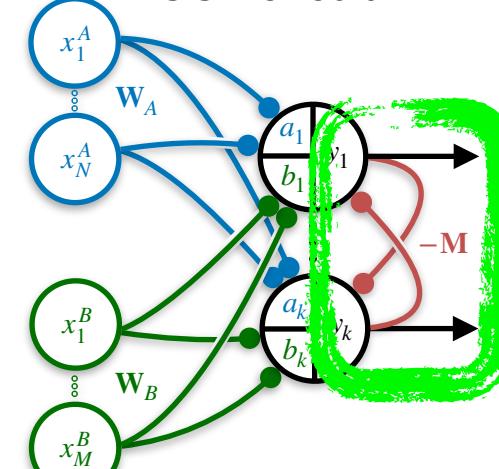
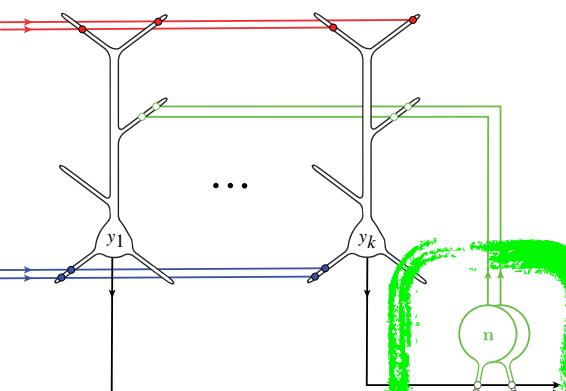


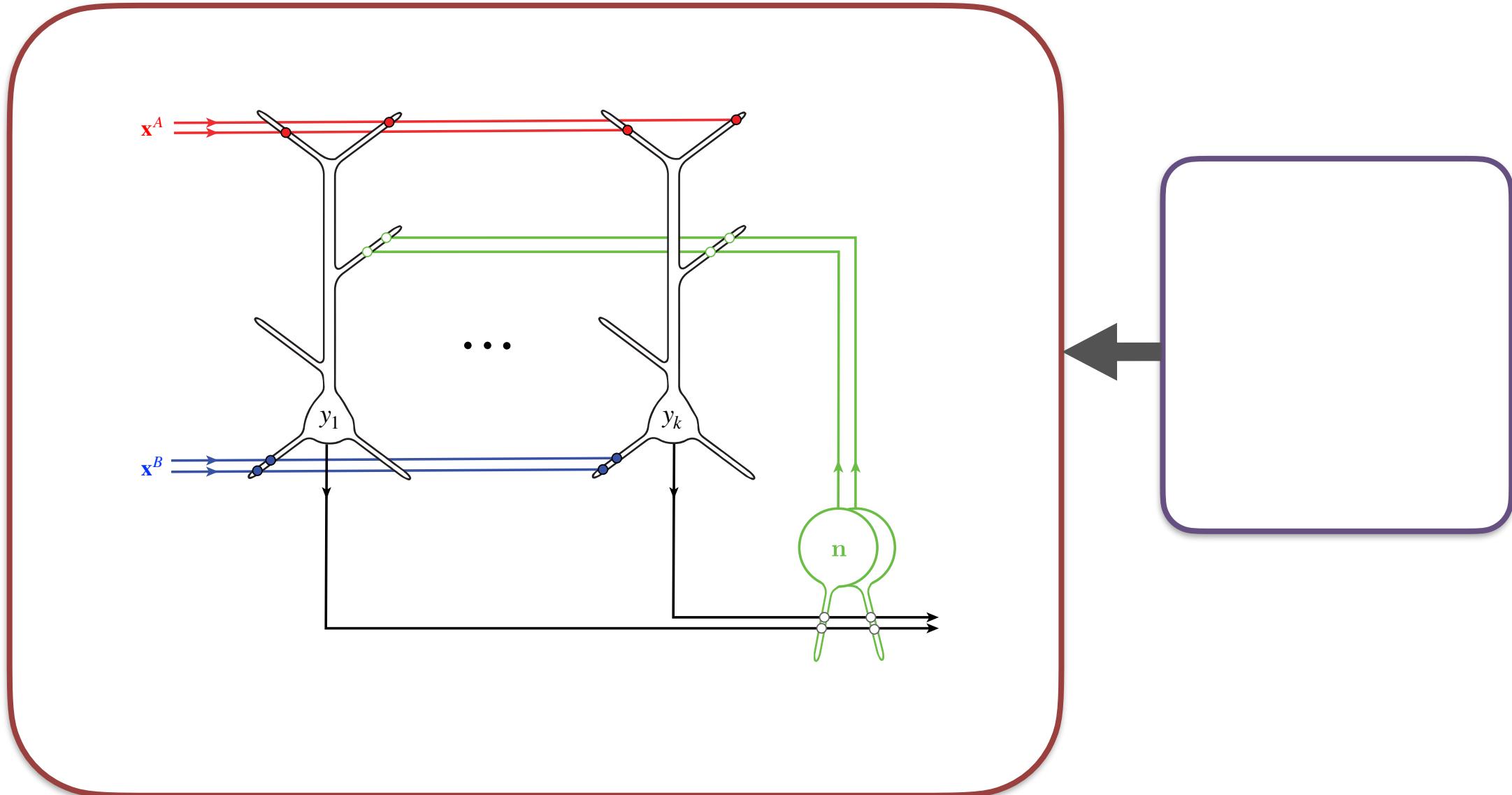
## CCA + output decorrelation

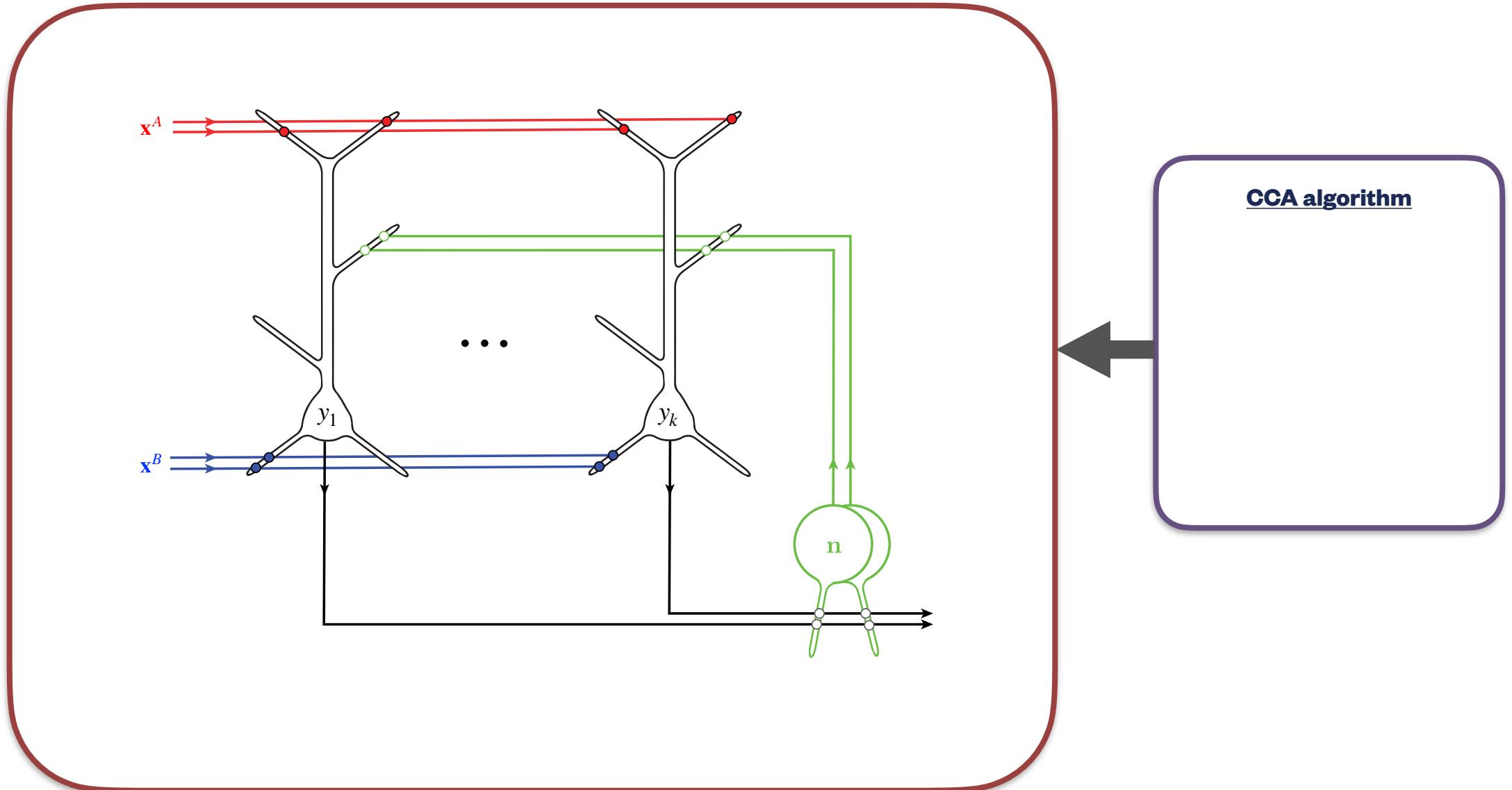
$$\min_{\mathbf{W}_a, \mathbf{W}_b} \max_{\mathbf{W}_n} \sum_{t=1}^T \min_{\mathbf{y}_t} \max_{\mathbf{n}_t} \ell(\mathbf{W}_a, \mathbf{W}_b, \mathbf{Q}, \mathbf{x}^A, \mathbf{x}^B, \mathbf{y}, \mathbf{n})$$

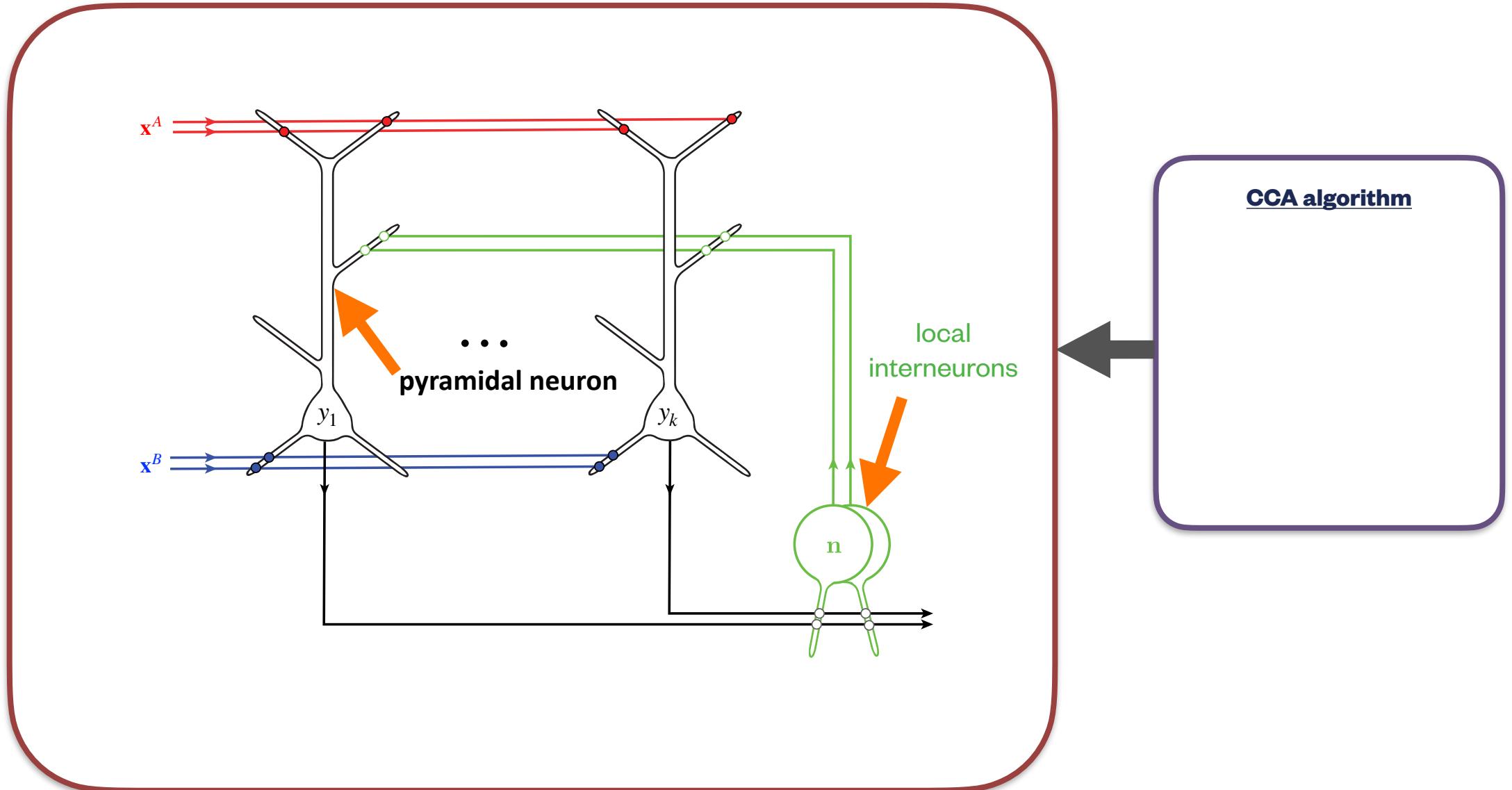
$$\begin{aligned} \ell(\mathbf{W}_a, \mathbf{W}_b, \mathbf{Q}, \mathbf{x}^A, \mathbf{x}^B, \mathbf{y}, \mathbf{n}) &= \mathbf{y}^\top \mathbf{y} - \mathbf{n}^\top \mathbf{n} \\ &\quad - 2\mathbf{y}^\top \mathbf{W}_a \mathbf{x}^A + \text{Tr} (\mathbf{W}_a \mathbf{W}_a^\top) \\ &\quad - 2\mathbf{y}^\top \mathbf{W}_b \mathbf{x}^B + \text{Tr} (\mathbf{W}_b \mathbf{W}_b^\top) \\ &\quad + 2\mathbf{n}^\top \mathbf{Q} \mathbf{y} - \text{Tr} (\mathbf{Q} \mathbf{Q}^\top) \end{aligned}$$

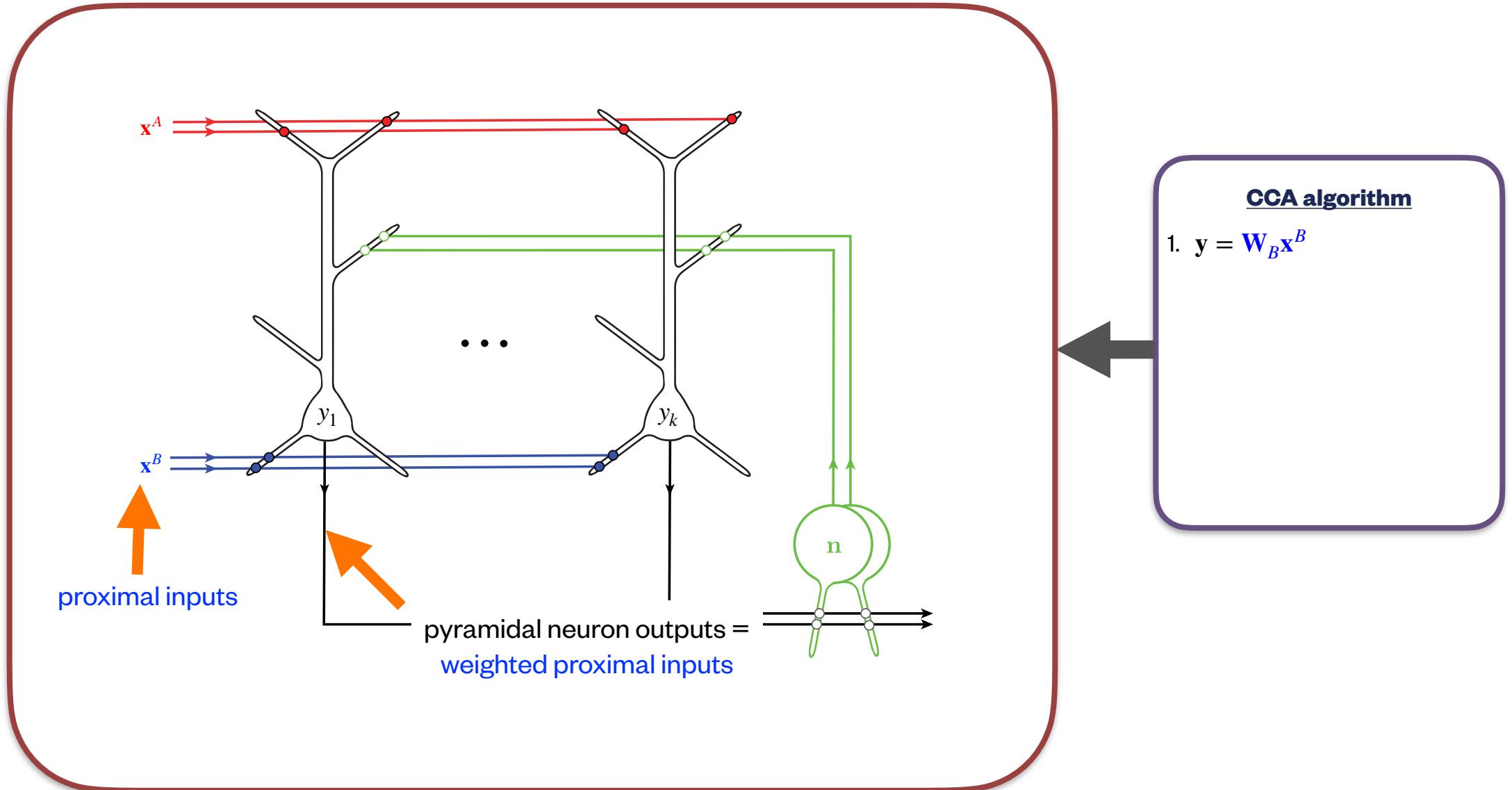
## CCA circuit

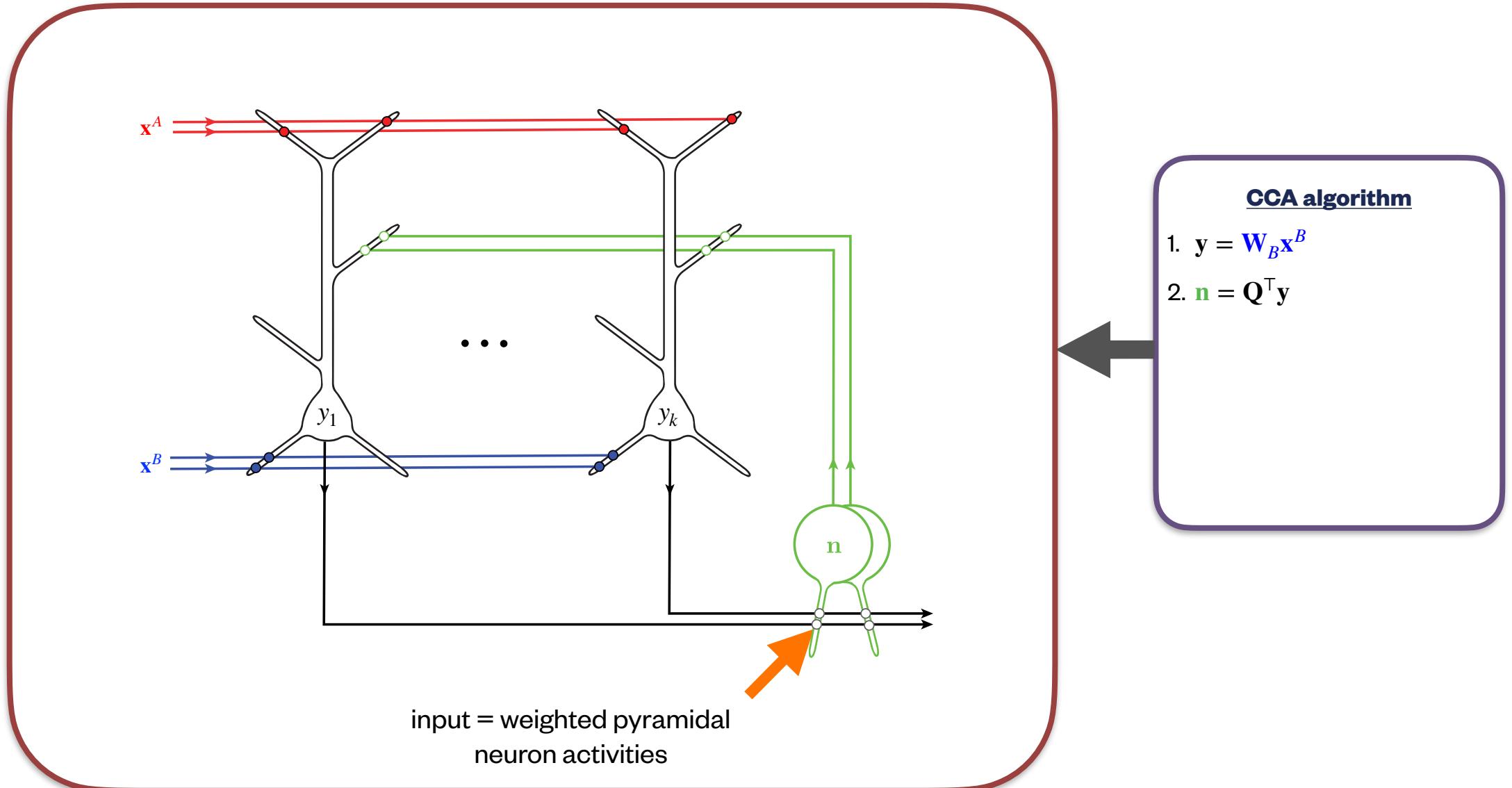
compare with  
cortical microcircuit

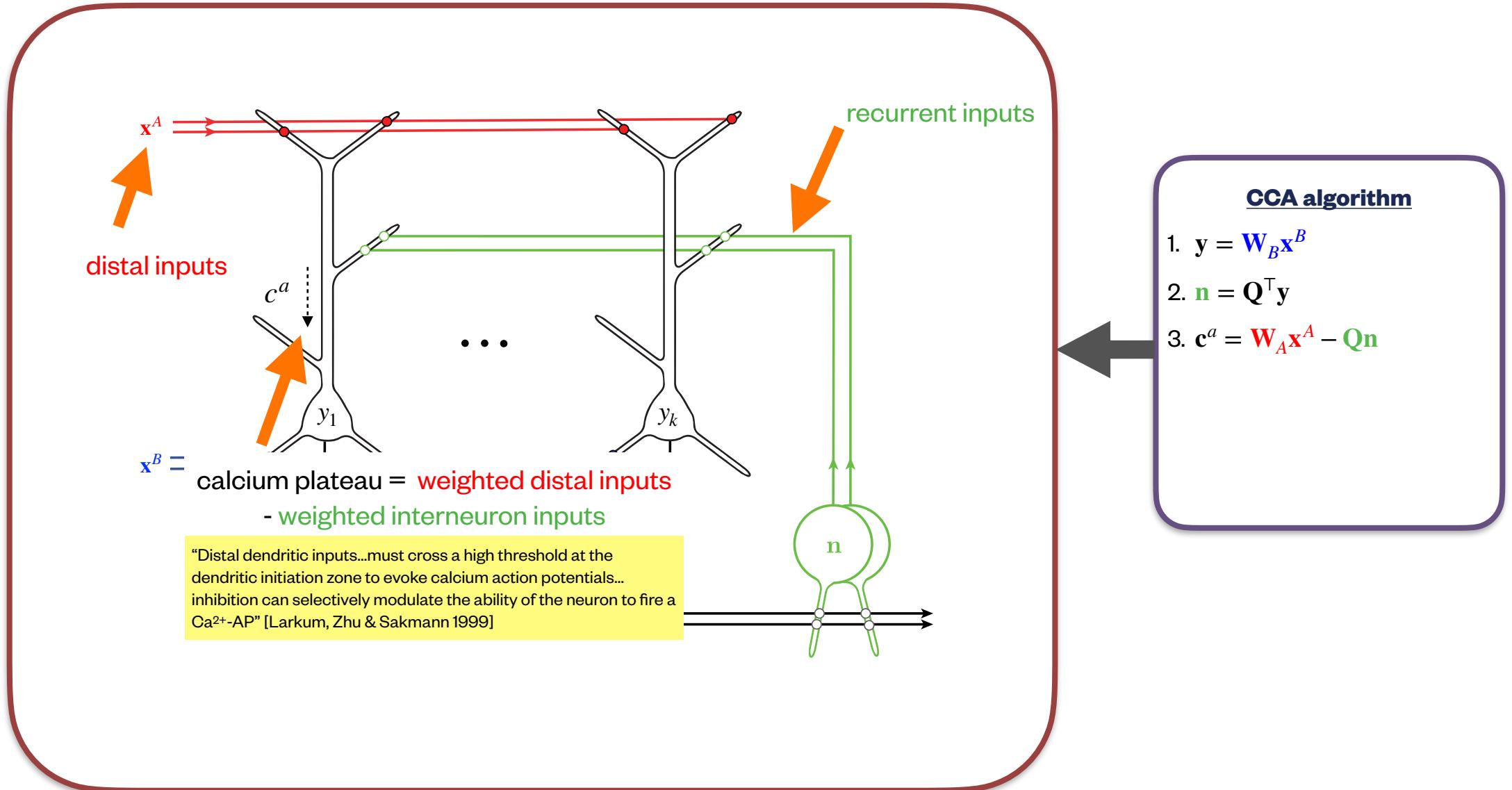


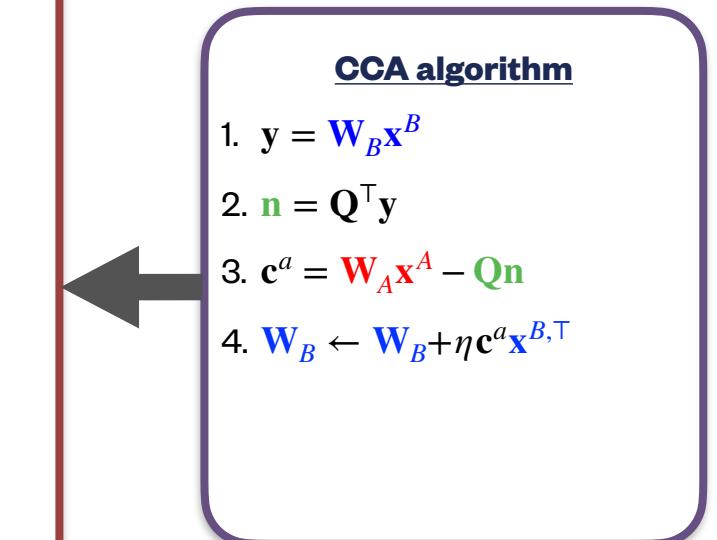
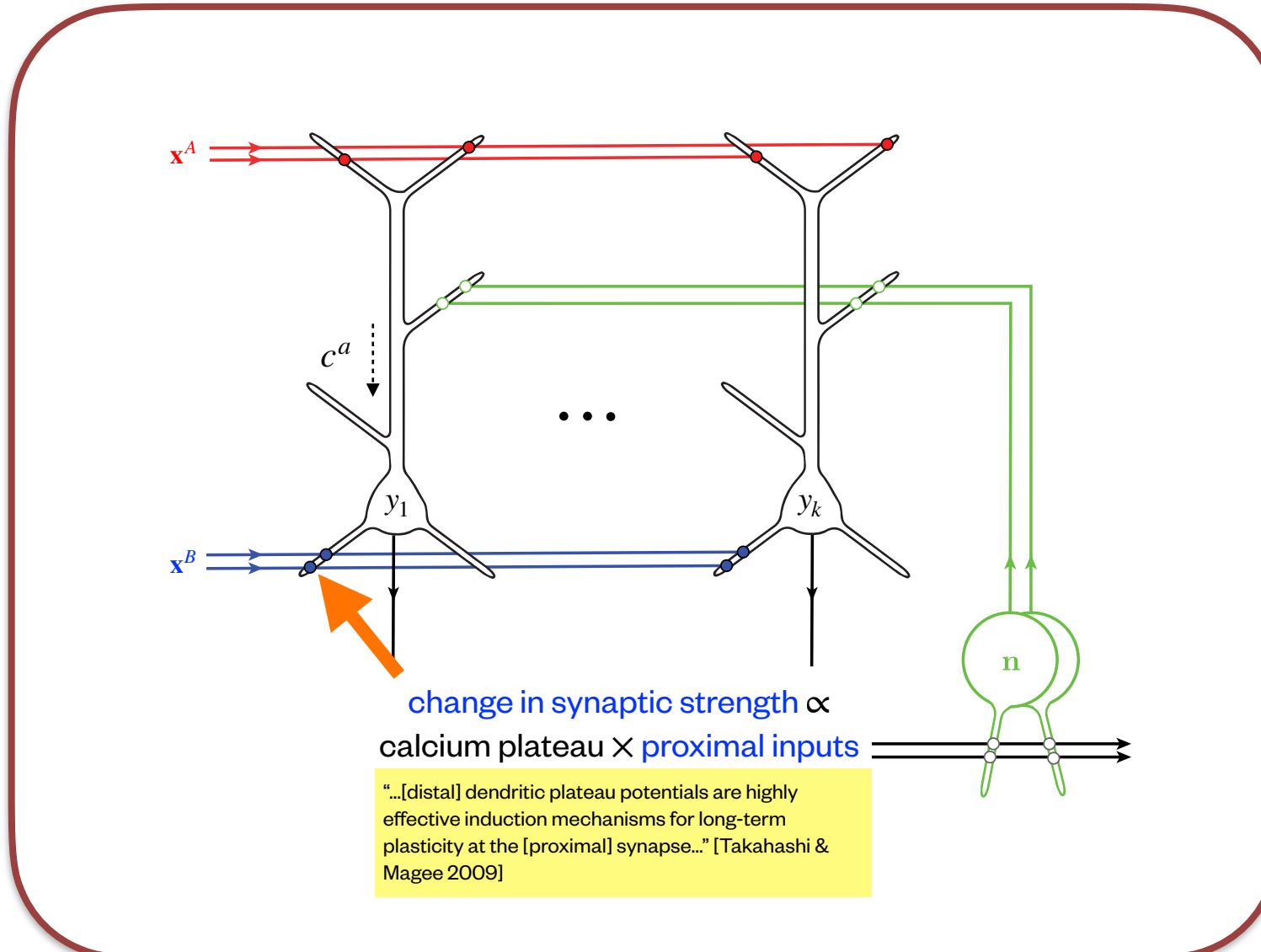


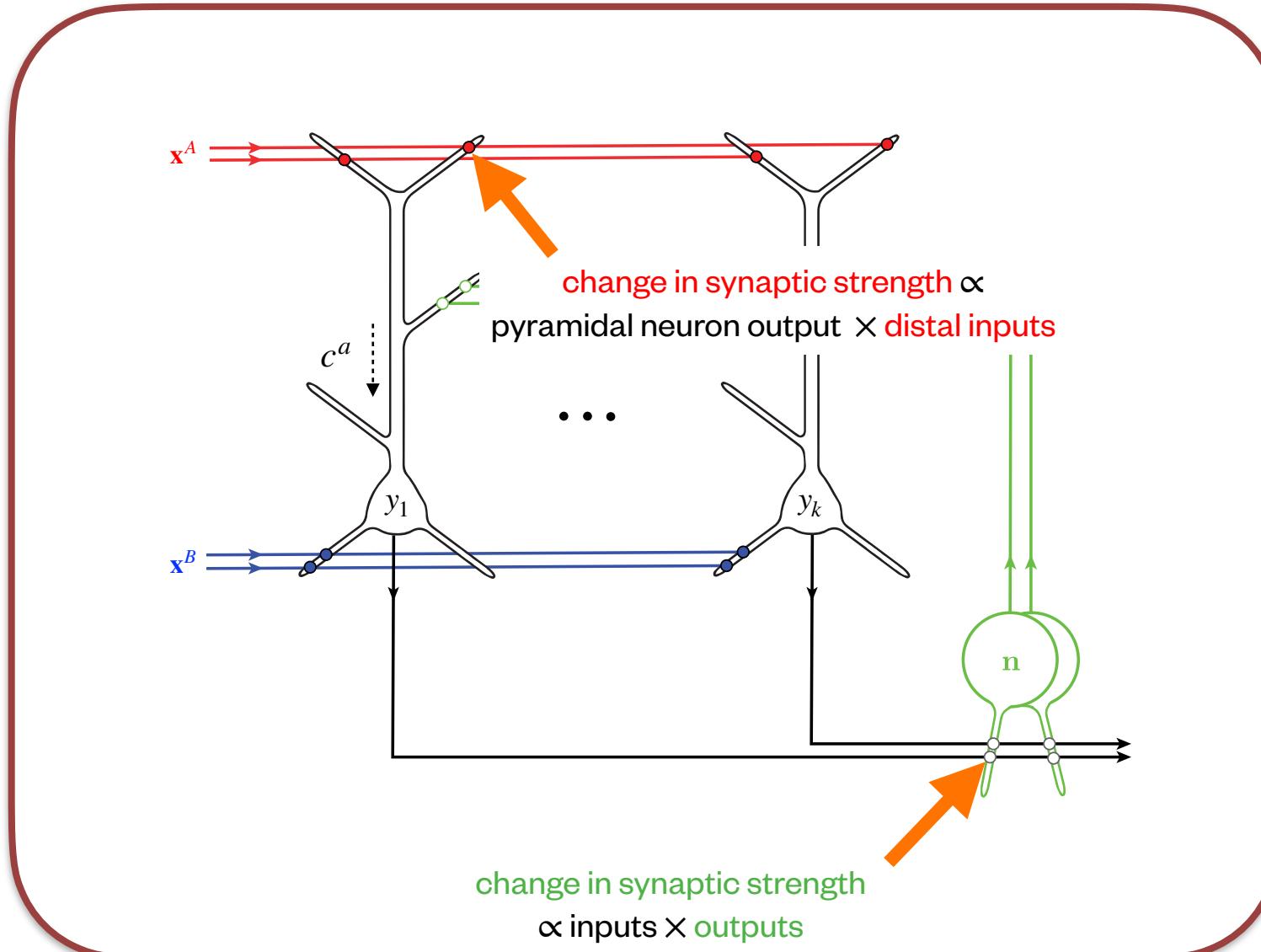






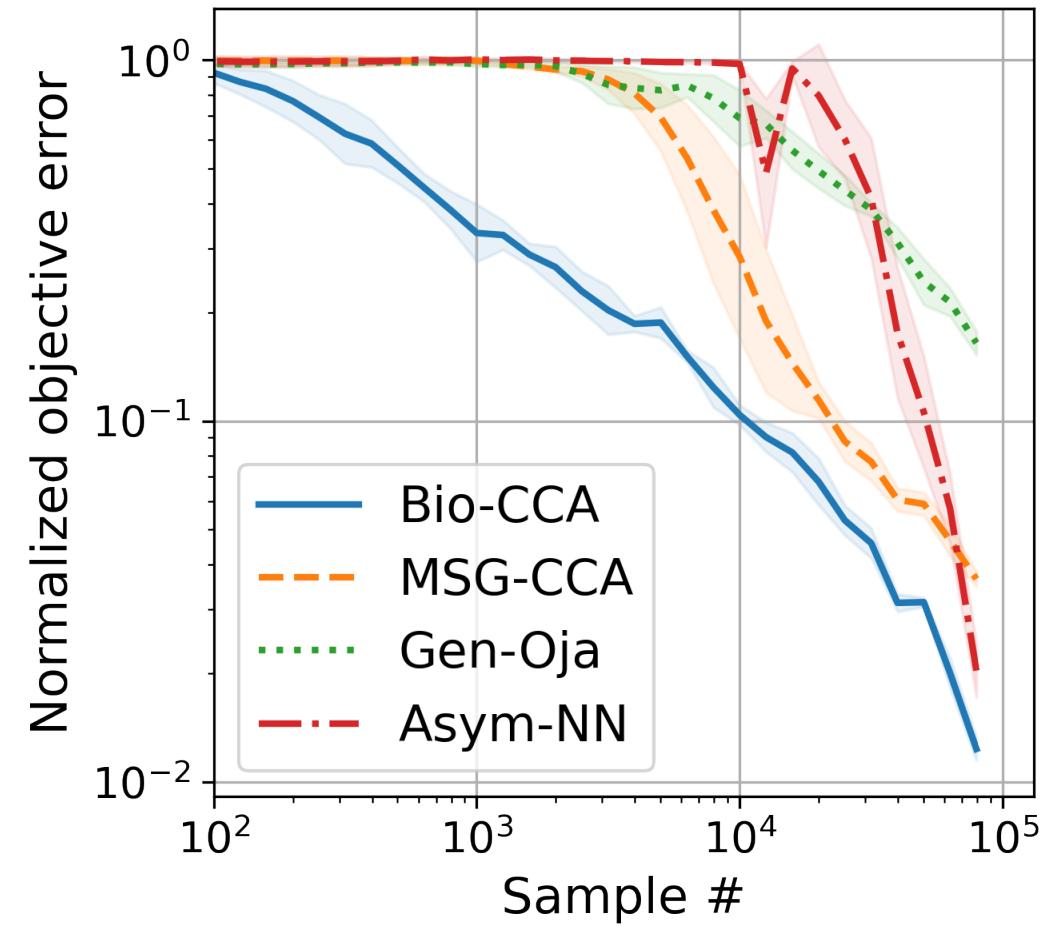


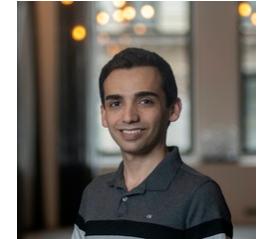


**CCA algorithm**

1.  $\mathbf{y} = \mathbf{W}_B \mathbf{x}^B$
2.  $\mathbf{n} = \mathbf{Q}^\top \mathbf{y}$
3.  $\mathbf{c}^a = \mathbf{W}_A \mathbf{x}^A - \mathbf{Qn}$
4.  $\mathbf{W}_B \leftarrow \mathbf{W}_B + \eta \mathbf{c}^a \mathbf{x}^{B,\top}$
5.  $\mathbf{W}_A \leftarrow \mathbf{W}_A + \eta (\mathbf{y} \mathbf{x}^{A,\top} - \mathbf{W}_A)$
6.  $\mathbf{Q} \leftarrow \mathbf{Q} + \frac{\eta}{\tau} (\mathbf{y} \mathbf{n}^\top - \mathbf{Q})$

Empirical evidence that the algorithm is sample efficient





# Interim summary

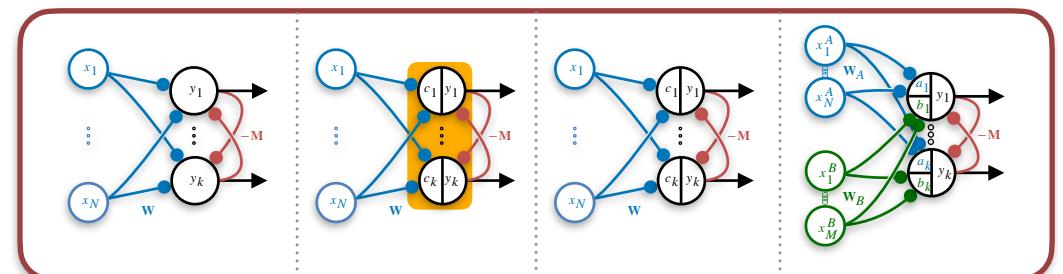
Proposed a general framework for relating learning principles to synaptic plasticity rules

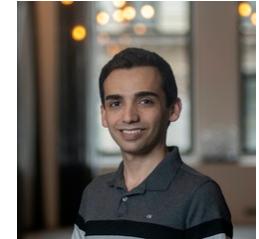
$$\mathbf{A}\mathbf{W} = \lambda\mathbf{B}\mathbf{W}$$

```

input  $\{(\xi_t, \mathbf{B}_t)\}$ ; parameters  $0 < \eta < \tau$ 
initialize  $\mathbf{W} \in \mathbb{R}^{k \times n}$  and  $\mathbf{M} \in \mathbb{S}_{++}^k$ 
for  $t = 1, 2, \dots$  do
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end for

```





# Interim summary

Proposed a general framework for relating learning principles to synaptic plasticity rules

Neural algorithms wish list:

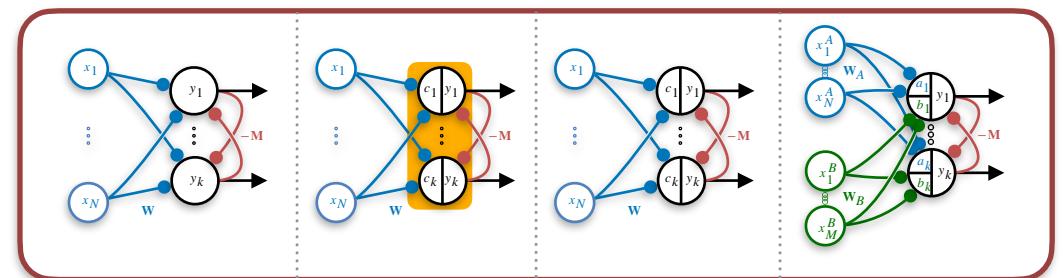
- principled? **yes**
- free parameters? **2**
- sample efficient? **yes (empirical)**
- resource efficient? **local & online**
- match data? **consistent with observations in the cortical microcircuit**

$$\mathbf{A}\mathbf{W} = \lambda\mathbf{B}\mathbf{W}$$

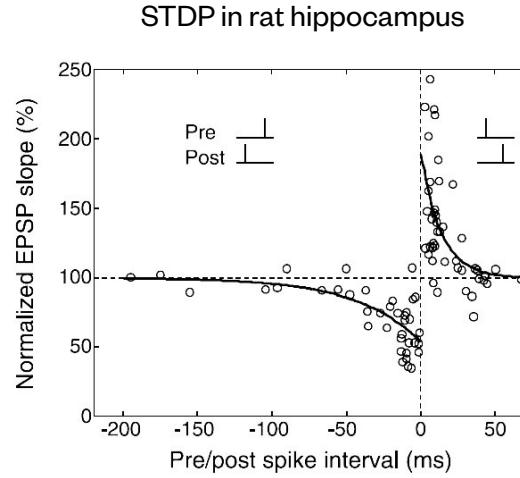
```

input  $\{(\xi_t, \mathbf{B}_t)\}$ ; parameters  $0 < \eta < \tau$ 
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end for

```

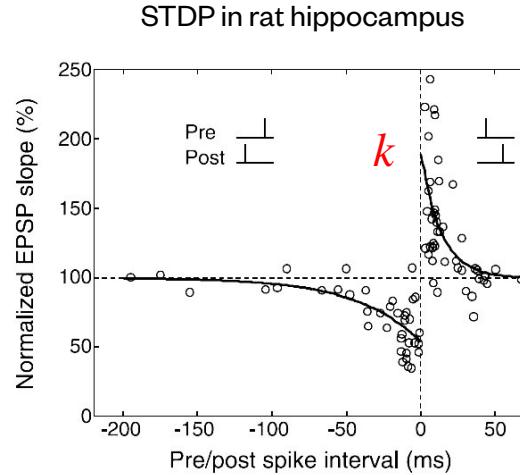


# What about spike-timing-dependent plasticity (STDP)?



[**Bi & Poo, 1998**; Feldman 2012]

# What about spike-timing-dependent plasticity (STDP)?

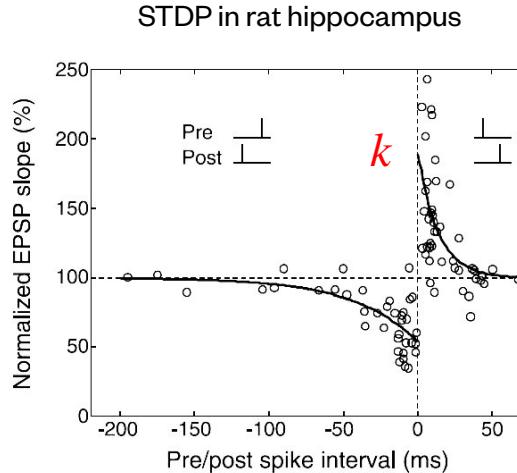


[**Bi & Poo, 1998**; Feldman 2012]

$$\mathbf{A}\mathbf{w} = \lambda \mathbf{B}\mathbf{w}$$

$$\mathbf{A} = \sum_{t,\tau} k(t-\tau) \mathbf{x}_t \mathbf{x}_\tau^\top, \quad \mathbf{B} = \sum_t \mathbf{x}_t \mathbf{x}_t^\top$$

# What about spike-timing-dependent plasticity (STDP)?



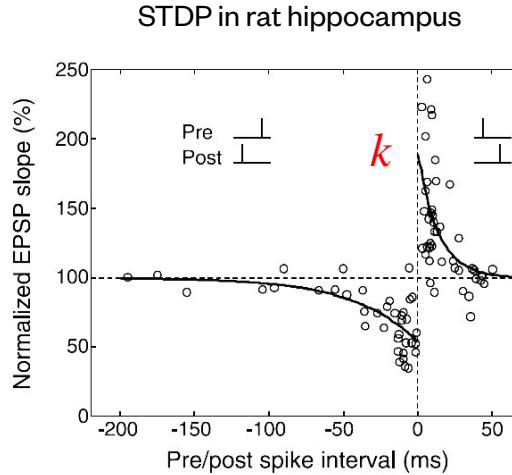
[Bi & Poo, 1998; Feldman 2012]

$$\mathbf{Aw} = \lambda \mathbf{Bw}$$

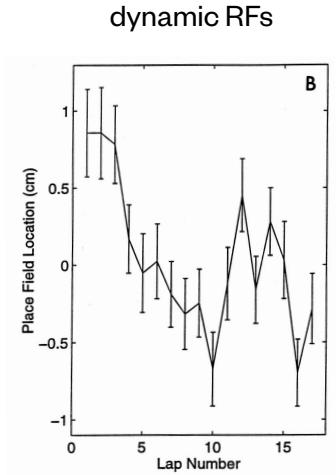
$$\mathbf{A} = \sum_{t,\tau} k(t - \tau) \mathbf{x}_t \mathbf{x}_\tau^\top, \quad \mathbf{B} = \sum_t \mathbf{x}_t \mathbf{x}_t^\top$$

- $\mathbf{A}$  is not **symmetric**, function of kernel / time reversibility
- eigenvectors are complex-valued
- dynamic receptive fields with speed  $\propto \text{Im}(\lambda_1)$

# What about spike-timing-dependent plasticity (STDP)?



[Bi & Poo, 1998; Feldman 2012]



[Mehta et al. 1997; Dong et al. 2021]

$$\mathbf{Aw} = \lambda \mathbf{Bw}$$

$$\mathbf{A} = \sum_{t,\tau} k(t - \tau) \mathbf{x}_t \mathbf{x}_\tau^\top, \quad \mathbf{B} = \sum_t \mathbf{x}_t \mathbf{x}_t^\top$$

- $\mathbf{A}$  is not **symmetric**, function of kernel / time reversibility
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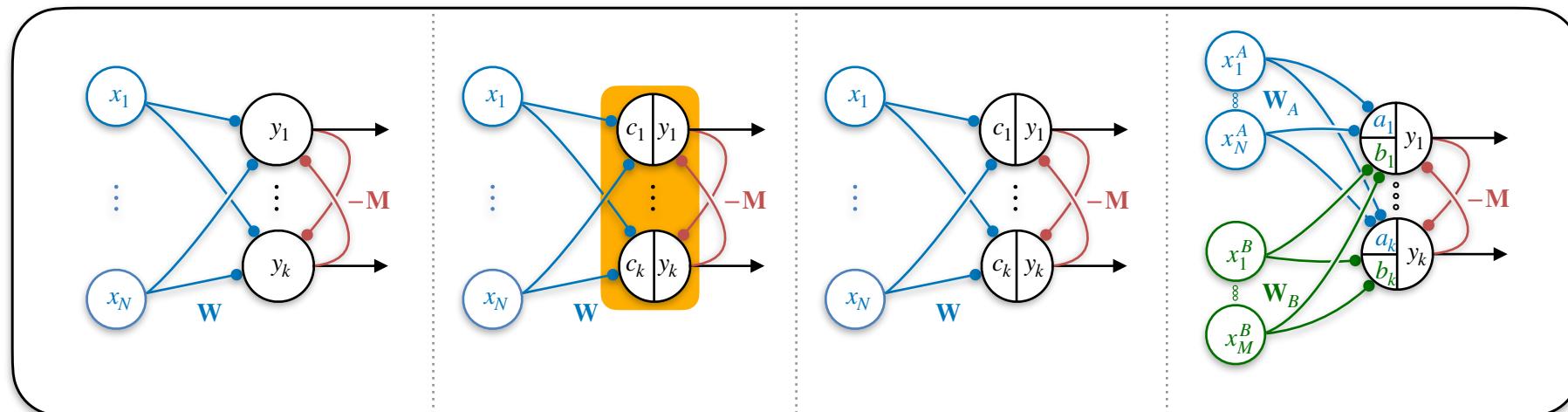
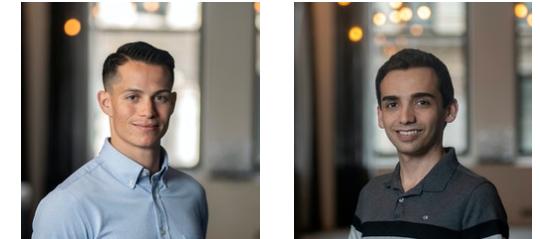
Goal: concise mathematical descriptions  
of the statistical learning algorithms that  
support sensory processing.

# Where do we go from here?

## Wish list for biological statistical learning algorithms:

1. sample efficient? optimize for sensory statistics
2. resource efficient? spiking?
3. no free parameters? match learning rates to environment
4. matches neural data? hierarchical, nonlinear processing,  
feedback, recurrence

# Thank you.



## Flatiron Institute

Yanis Bahroun  
Siavash Golkar  
Charles Windolf  
Tiberiu Tesileanu  
Anirvan Sengupta  
Dmitri Chklovskii